

Seminar on Graphs, Algorithms and Optimization:  
**A Fast Parametric Maximum Flow Algorithm  
and Applications**

(Gallo, Grigoriadis, Tarjan, 1989)

Sandro M. Roch

02.07.2020

# Parametric Maximum Flow Problem

**Given:** Directed Graph  $(V, E)$

Source  $s \in V$ , Sink  $t \in V$ .

Capacities  $c_\lambda(v, w) \geq 0$  for all  $(v, w) \in E$ ,

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**Problem for  $\lambda \in \mathbb{R}$ :**

$$\kappa(\lambda) = \max \sum_{v \in V} f(v, t)$$

s.t.  $f(v, w) = -f(w, v)$  for all  $(v, w) \in V \times V$  (antisymmetry)

$f(v, w) \leq c_\lambda(v, w)$  for all  $(v, w) \in V \times V$  (capacity)

$\sum_{w \in V} f(w, v) = 0$  for all  $v \in V \setminus \{s, t\}$  (conservation)

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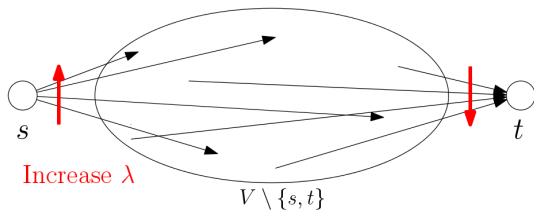
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Problem class too general to expect interesting parametric algorithm

$\Rightarrow$  Will restrict to subclass

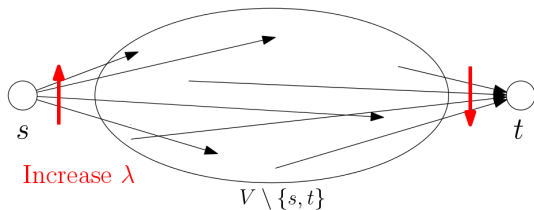
## Restrictions on parametric capacities:

- $\lambda \mapsto c_\lambda(s, v)$  non-decreasing for all  $v \in V$
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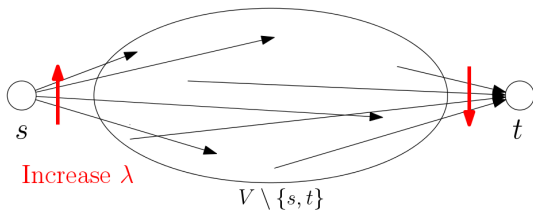
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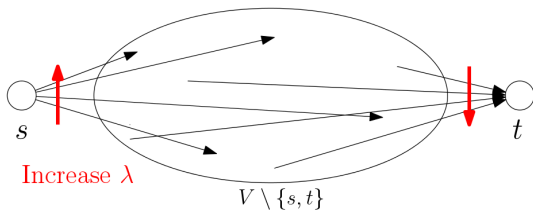
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- **Outline:** Modify Goldberg-Tarjan to obtain parametric algorithm that calculates  $\kappa(\lambda)$  for  $\lambda_1 \leq \dots \leq \lambda_l$  at once.



## Definition

- A *preflow*  $f : V \times V \rightarrow \mathbb{R}$  satisfies

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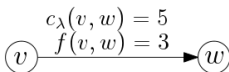
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**Remark:** Flows are the feasible solutions of the LP  
(*conservation* instead of *leaky conservation*)

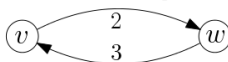
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- $d_f(v, w)$ : Number of arcs of shortest residual path from  $v$  to  $w$  or  $\infty$ .

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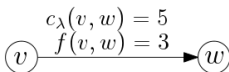
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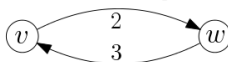
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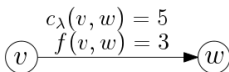
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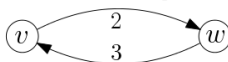
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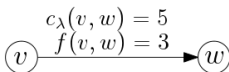
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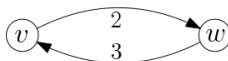
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- For all active nodes  $v$ :  $\min\{d_f(v, t), d_f(v, s) + n\} \leq 2n - 1$



**Claim:** Flow  $f$  has valid labeling  $d \Rightarrow f$  is maximal flow.

- If  $f$  not maximal: Exists residual path from  $s$  to  $t$  of length  $\leq n - 1$
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## Goldberg-Tarjan algorithm

- **Initialize** preflow  $f$  and valid labeling  $d$ .
- As long as exist active nodes:  
Eliminate active node by push-relabel-operation  
(might create new active nodes).
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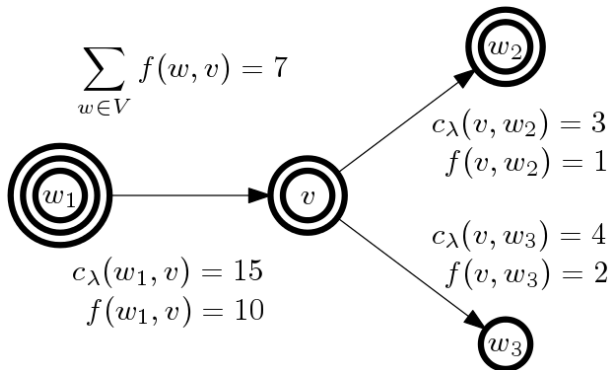
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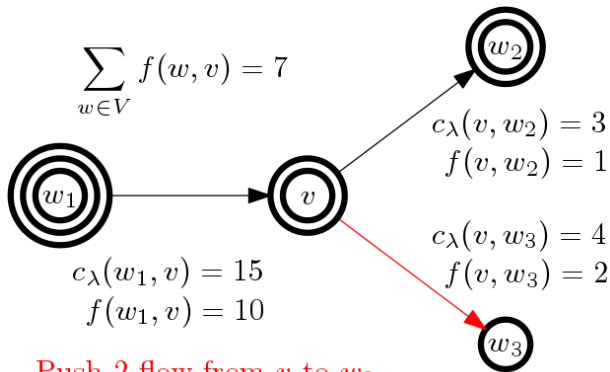
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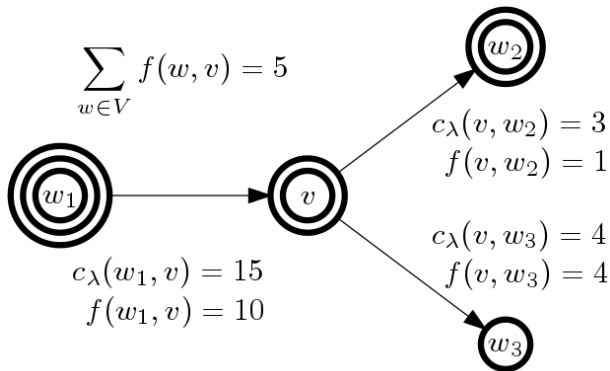
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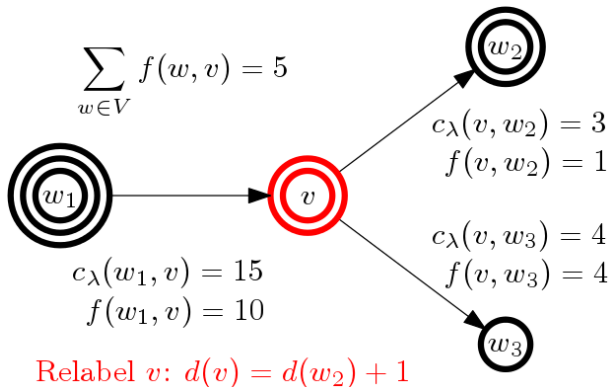
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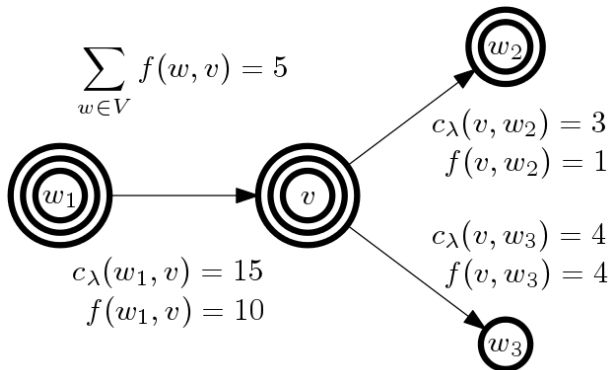
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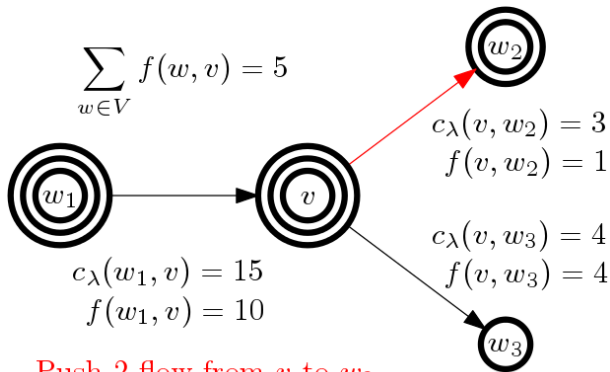
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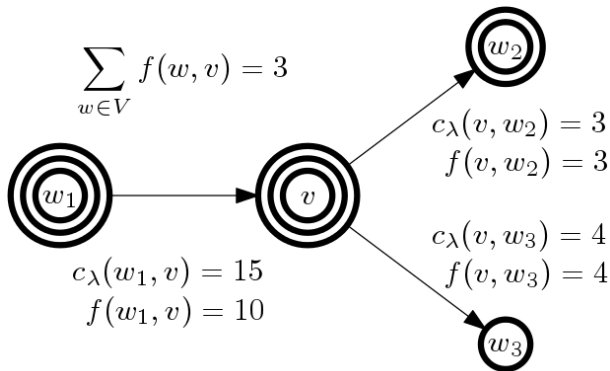
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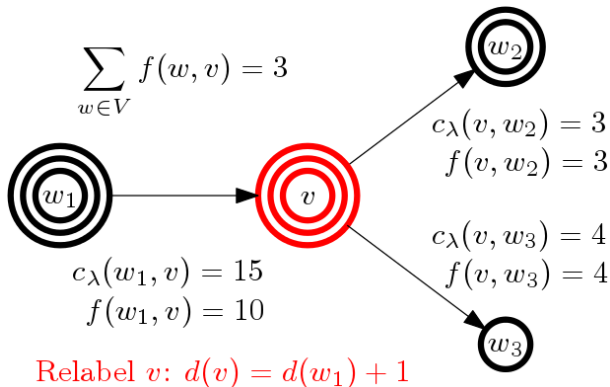




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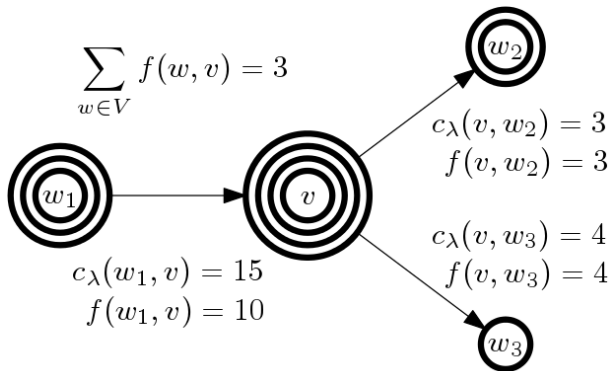
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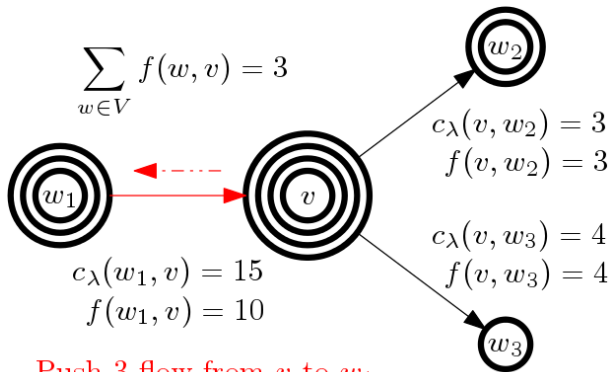
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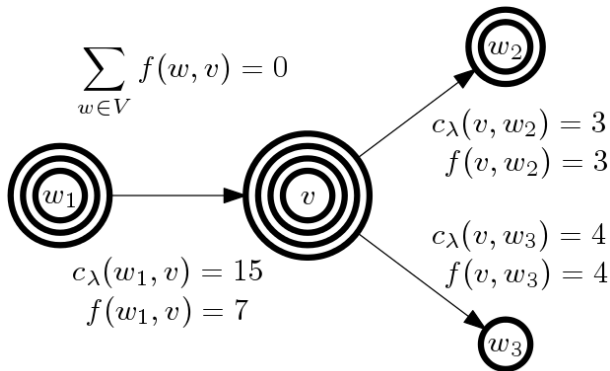
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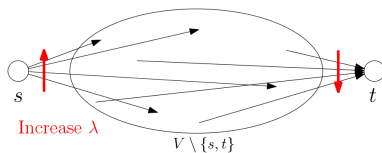
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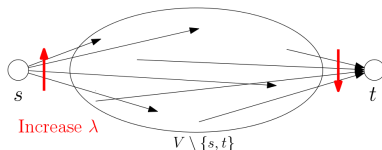
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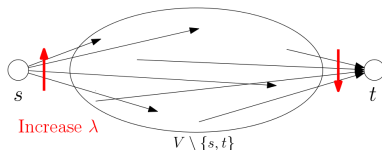
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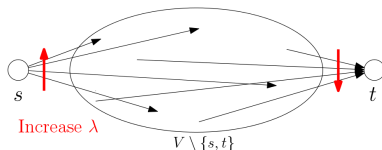


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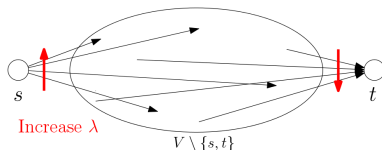
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- Observe:  $f'$  is indeed preflow and  $d$  valid labeling for  $f'$ .
- Run Goldberg Tarjan for  $\lambda_2$ , but start with  $f'$  and  $d$ .

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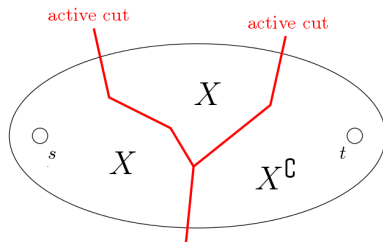
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# Parametric Goldberg Tarjan Algorithm

**Input:** Directed graph  $(V, E)$ ;  $s, t \in V$ ; capacities  $c_\lambda$ ;  $\lambda_1 \leq \dots \leq \lambda_l$

**Output:** MaxFlow  $f_i$  and MinCut  $(X_i, X_i^c)$  for  $i = 1, \dots, l$

Initialize  $f = 0$ ;  $d(s) \leftarrow n$ ;  $d(v) \leftarrow 0$  f.a.  $v \neq s$

for  $i = 1, \dots, l$  do

**Step 1: Update preflow**

$$f(v, w) \leftarrow \begin{cases} \min\{c_{\lambda_i}(v, t), f(v, t)\} & \text{if } w = t \\ \max\{c_{\lambda_i}(s, w), f(s, w)\} & \text{if } v = s \text{ and } d(w) < n \\ f(v, w) & \text{otherwise} \end{cases}$$

**Step 2: Run Goldberg Tarjan**

$$(f, d) \leftarrow \text{GoldbergTarjan}(f, d)$$

**Step 3: Find MinCut**

$$d(v) \leftarrow \min\{d_f(v, s) + n, d_f(v, t)\} \text{ for } v \in V$$

$$X \leftarrow \{v \in V \mid d(v) \geq n\}$$

**Output** „ $X_i = X, f_i = f$ “

end

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## Proof of 1):

- Correctness from discussion before
- Step 1 (Update preflow) requires  $\mathcal{O}(m)$  per iteration
- Step 2 (Goldberg Tarjan)  $\mathcal{O}(nm)$  + #non-saturating pushes
- Step 3 (Find MinCut) requires  $\mathcal{O}(m)$  per iteration
- $\Sigma$ :  $\mathcal{O}((n + l)m)$  + #non-saturating pushes
- As in ADM I: #non-saturating pushes  $\in \mathcal{O}(n^2(l + m))$
- In total: Running time  $\mathcal{O}(n^2(l + m))$

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## Proof of 2):

- Throughout execution,  $d$  only increases.
- Cut is chosen as  $X_i = \{v \in V \mid d(v) \geq n\}$

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## Corollary

*If  $l \in \mathcal{O}(n)$ , the asymptotic running time of the Parametric Goldberg Tarjan algorithm is the same as for the normal Goldberg Tarjan algorithm.*

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### Remark:

- Improve both to  $\mathcal{O}((n + l)m \log \frac{n^2}{m})$  by advanced strategies for push-relabel operations and advanced data structures.
- Parametric Goldberg Tarjan algorithm works **on-line** for sequence  $\lambda_1 \leq \dots \leq \lambda_l$ .

# Maximization of $\kappa(\lambda)$

- **Goal:** Determine  $\lambda \in \mathbb{R}$  so that  $\lambda \mapsto \kappa(\lambda)$  maximal
- Assume  $\lambda \mapsto c_\lambda(v, w)$  affine linear for all  $(v, w) \in V \times V$

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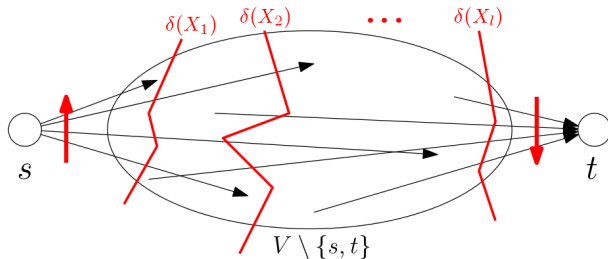
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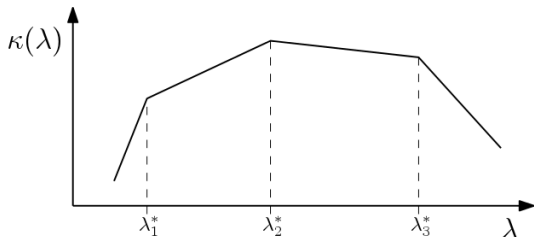
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**Proof:** Follows directly from nested property  $X_1 \subseteq X_2 \subseteq \dots \subseteq X_l$ .



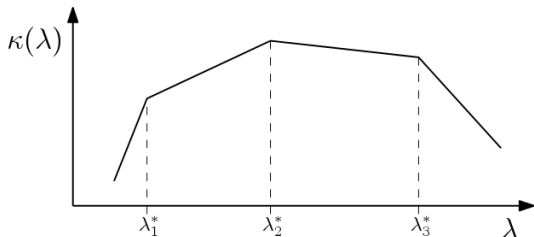
**Recall** from ADM II (Global Dependence on the Cost Vector):

- $\kappa(\lambda)$  is concave and piecewise linear.
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**Consequence:**

- Now basis change means change of MinCut  $(X, X^C)$ .
- Therefore at most  $n - 1$  breakpoints.

## Calculate the line segments of $\kappa(\lambda)$ :

- Assume parametric capacities are given for  $v \in V \setminus \{s, t\}$  by

$$c_\lambda(s, v) = a_0(v) + \lambda \cdot a_1(v)$$

$$c_\lambda(v, t) = b_0(v) - \lambda \cdot b_1(v)$$

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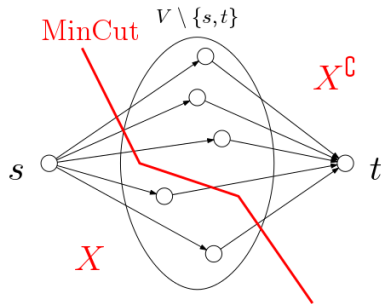
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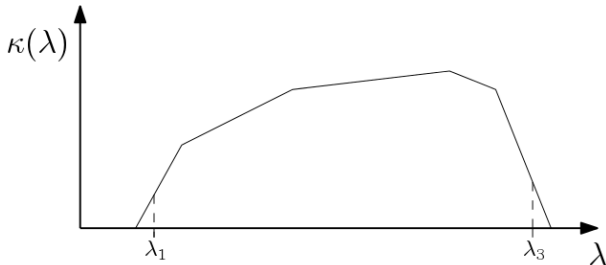
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- Line segment of  $\kappa(\lambda)$  around  $\lambda_0$ :

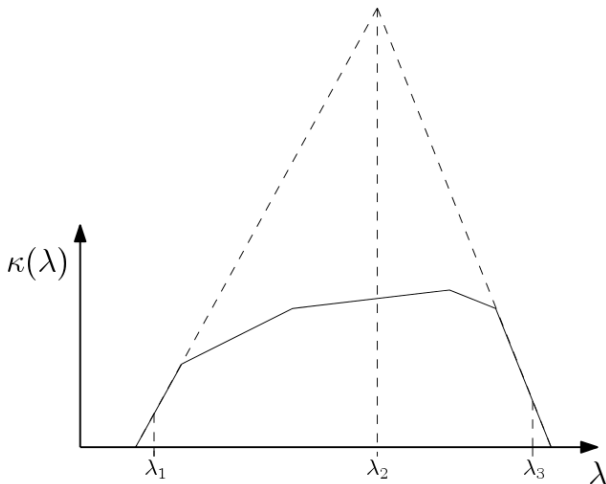
$$L(\lambda) = \kappa(\lambda_0) + (\lambda - \lambda_0) \cdot \left( \sum_{v \in X^c \setminus \{t\}} a_1(v) - \sum_{v \in X \setminus \{s\}} b_1(v) \right)$$



**Example:** Assume  $\lambda_{\max} \in [\lambda_1, \lambda_3]$ :

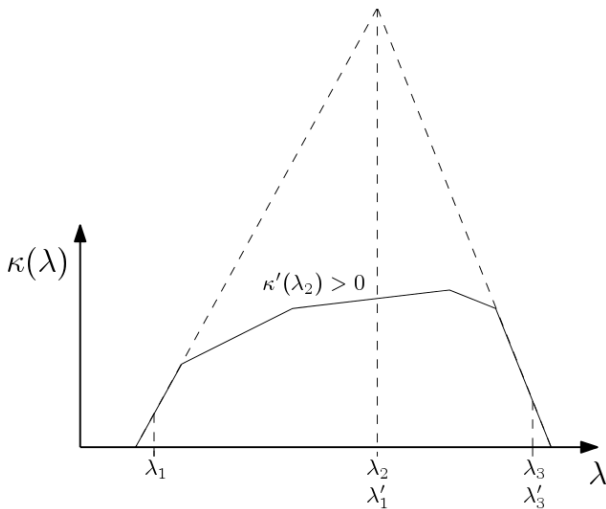


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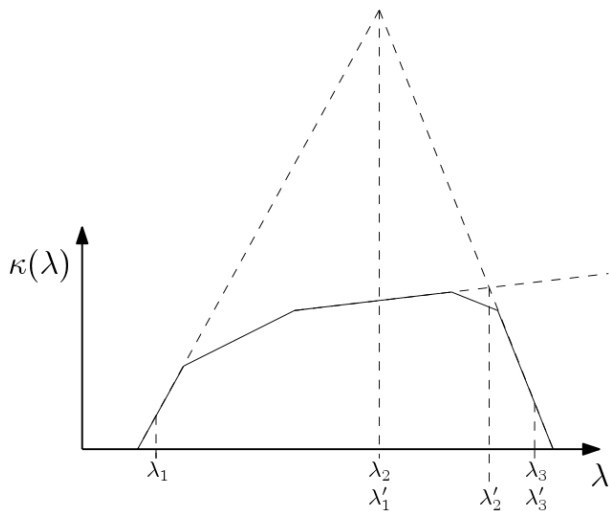




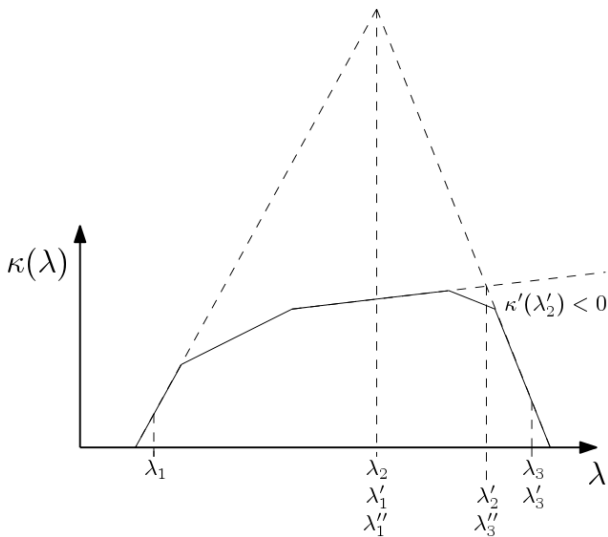
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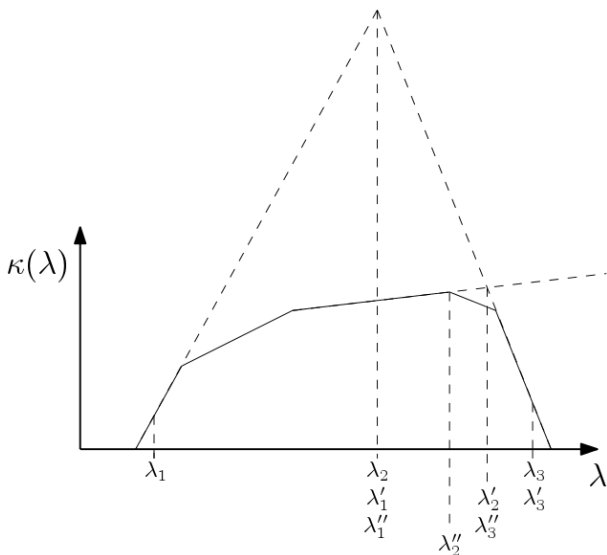
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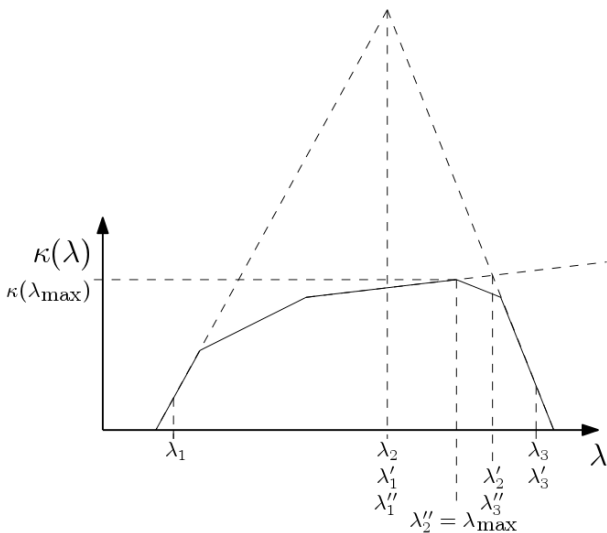
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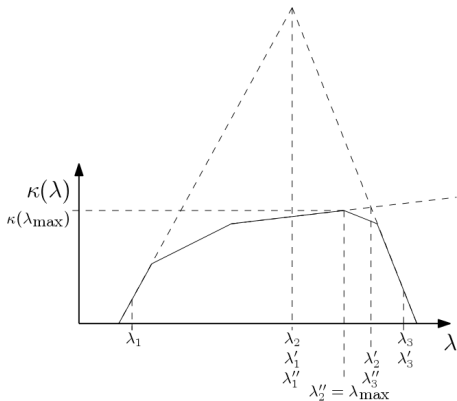


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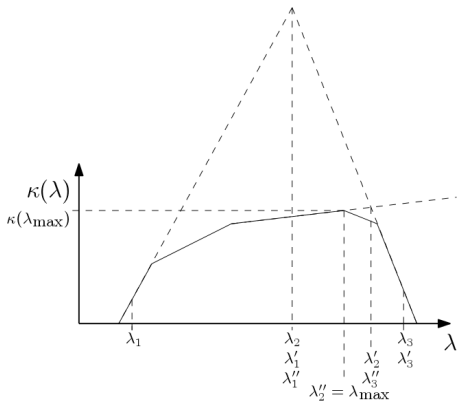
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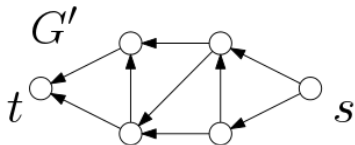
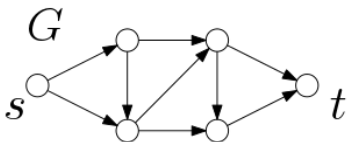


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- For calculating  $\kappa(\lambda)$  for  $\lambda_1 \leq \lambda'_1 \leq \lambda''_1 \leq \dots$  and  $\lambda_3 \geq \lambda'_3 \geq \lambda''_3 \geq \dots$  use two concurrent runs of Parametric Goldberg Tarjan.

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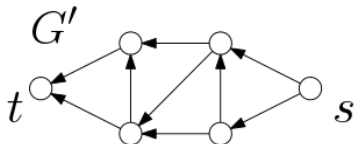
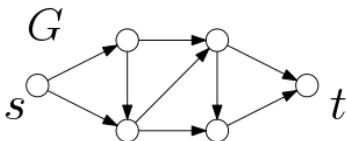
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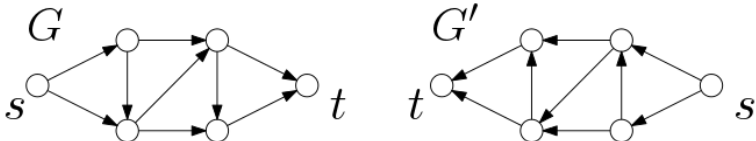
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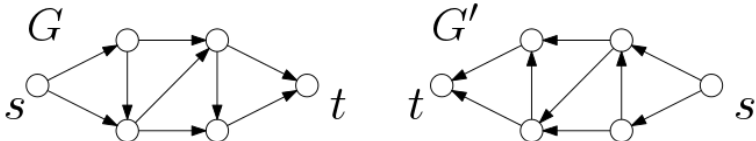
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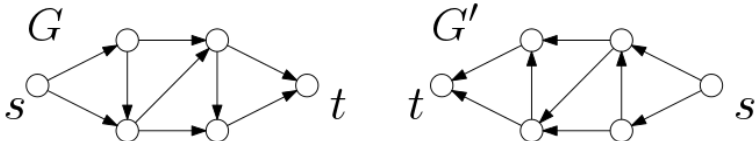
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- Apply Parametric Goldberg Tarjan on  $G'$ .

## Application: Flow sharing

**Given:** Directed Graph  $(V, E)$  with capacities  $c \in \mathbb{R}^E$   
Multiple sources  $s_1, \dots, s_k \in V$ , sink  $t \in V$   
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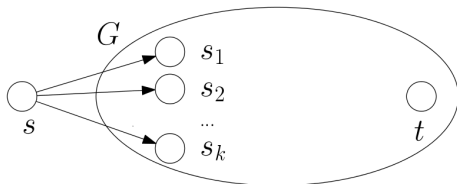
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**Perfect sharing:**

- Restrict to flows with equal ratios  $\frac{u_1}{w_1}, \dots, \frac{u_k}{w_k}$ .
- Find maximal flow under this restriction.

## Solving perfect sharing:

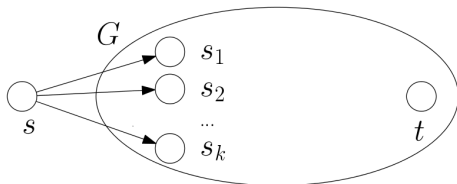
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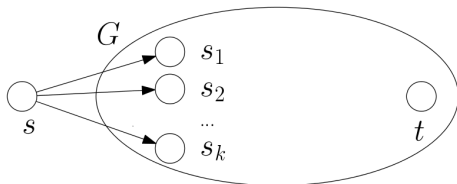
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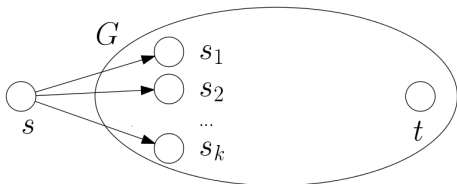
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- $\text{MinCut} = (\{s\}, V)$  iff  $\lambda \leq \lambda_0$ .

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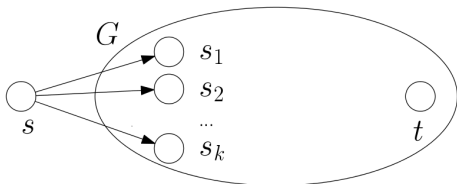


- Find smallest breakpoint  $\lambda_0$  of  $\kappa(\lambda)$  by similar algorithm.
- $\text{MinCut} = (\{s\}, V)$  iff  $\lambda \leq \lambda_0$ .
- For  $\lambda \leq \lambda_0$  have perfect sharing, since for all  $i$ :

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- $\lambda_0$  maximizes MaxFlow under perfect sharing.

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Parametric Goldberg Tarjan can solve all of them!

- Gallo, Grigoriadis & Tarjan (1989). *A fast parametric maximum flow algorithm and applications*. SIAM J. Comput. 18 (1), pp. 30