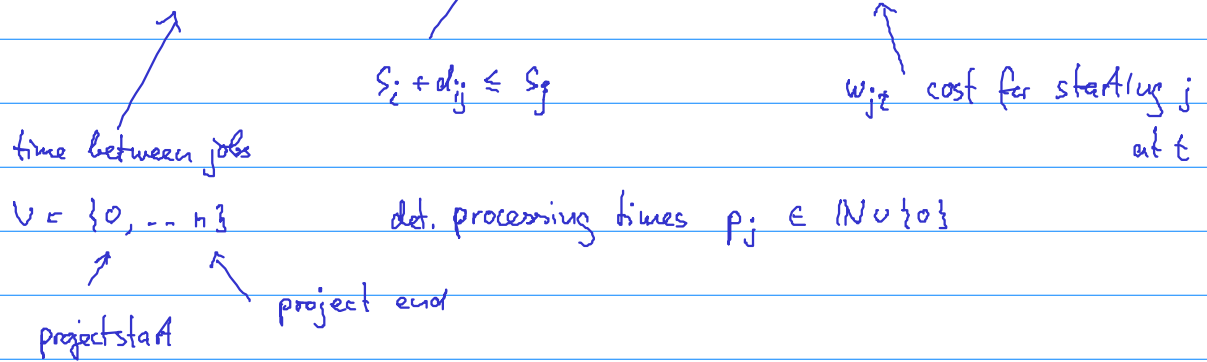
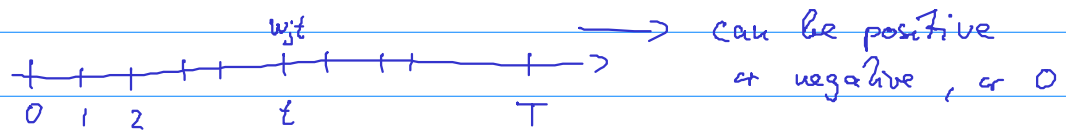


B Project scheduling with time lags and start dependent cost



$p_0 = p_n = 0$ time lags with 0, n can be arbitrary



min \sum_j (start time cost of j) over all feasible schedules
 (assume \exists feasible schedule)

Formulation as IP

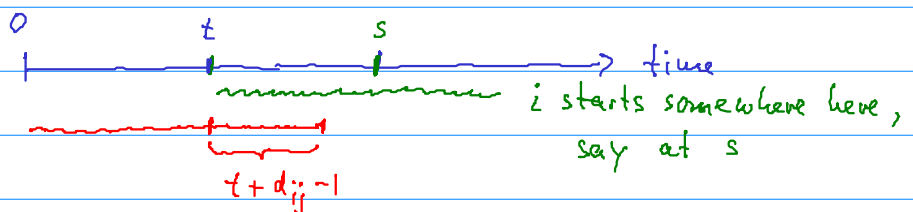
$$x_{jt} = \begin{cases} 1 & \text{if } j \text{ is started at } t \\ 0 & \text{otherwise} \end{cases}$$

$$\min \sum_j \sum_t w_{jt} x_{jt} \quad (1)$$

$$\text{s.t. } \sum_t x_{jt} = 1 \quad \forall j \quad \text{every job is started exactly once} \quad (2)$$

$$\sum_{s=t}^T x_{is} + \sum_{s=0}^{t+d_{ij}-1} x_{js} \leq 1 \quad \forall (i,j) \in L \quad \forall t \quad (3)$$

every time lag $S_i + d_{ij} \leq S_j$ is respected



so if i starts at a and j at b
 and $a + d_{ij} > b$, then (3) is violated for $t = a$

$$x_{jt} \in \{0, 1\} \quad (4)$$

We can compute in advance

- earliest start $e(j) \geq 0 \quad \forall j$
- latest start $l(j) \leq T - p_j \quad \forall j$

Because of (2), we lift all w_{jt} by a constant M such that

$$\bar{w}_{jt} := w_{jt} + M \geq 0$$

This changes the objective only by the constant $(n+1)M$

\Rightarrow will assume w.l.o.g. that $w_{jt} \geq 0$

Transformation into a min cut problem

$D = (N, A)$ is the graph for the min cut problem

Nodes: one for every possible start time of every job and $l(j) + 1$

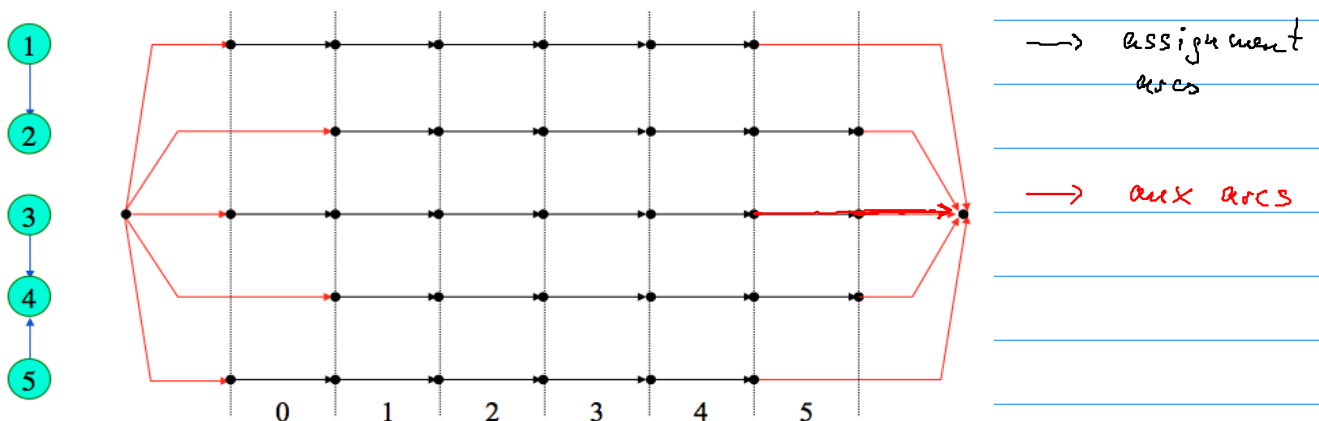
+ source a , sink b

$$\Rightarrow N = \{ v_{jt} \mid j \in V, t = e(j), e(j)+1, \dots, l(j)+1 \} \cup \{ a, b \}$$

Arco $A = \{ \text{assignment arcs} \} \cup \{ \text{temporal arcs} \} \cup \{ \text{auxiliary arcs} \}$

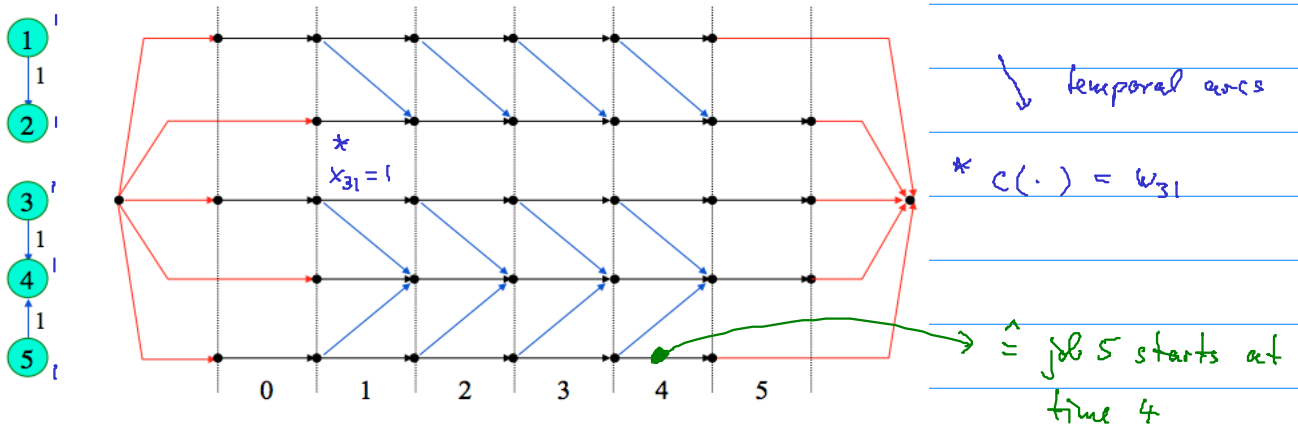
assignment arcs: $(v_{jt}, v_{j,t+1}) \quad \forall j \in V$

auxiliary arcs: $(a, v_{j,e(j)}) \quad (v_{j,l(j)+1}, b) \quad \forall j \in V$



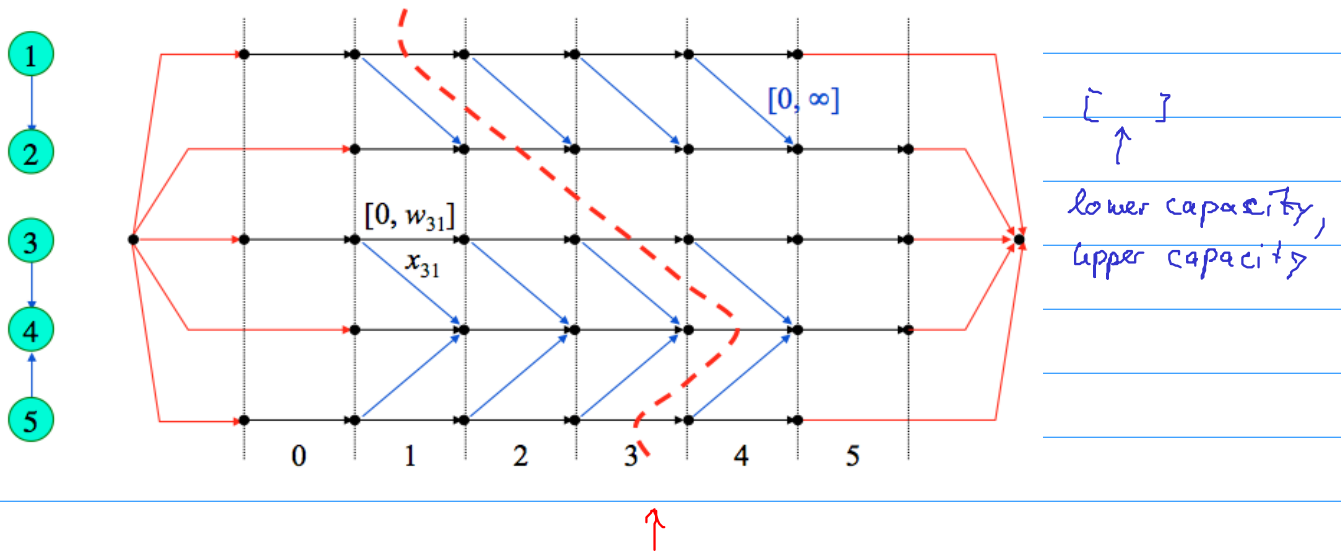
all $p_j = 1$, all $d_{ij} = 1$ $T = 6$

Temporal arcs $(V_{i,t}, V_{j,t+d_{ij}}) \forall$ time lags $(i,j) \in L$
 $\forall t$ with $e(i)+1 \leq t \leq l(i)$
 $e(j)+1 \leq t+d_{ij} \leq l(j)$



Idea: use assignment arcs to indicate the start of a job

arc capacities: assignment arcs: $c(V_{j,t}, V_{j,t+1}) = w_{j,t}$
 other arcs $c(\cdot) := \infty$
 all lower capacities are 0



such a cut will induce start times
 (maybe infeasible)

For our result, we are interested in special cuts, so called n -cuts.
 An n -cut contains exactly one forward arc for every job

21.2 Lemma (n-cuts are the important ones)

Let (X, \bar{X}) be a minimum (a, b) -cut and $c(X, \bar{X}) < \infty$

Then \exists an n-cut with the same value

It can be computed from (X, \bar{X}) in $O(n \cdot T)$ time

Proof

(1) (X, \bar{X}) contains at least one assignment arc for every job
obvious

(2) if (X, \bar{X}) contains more than one assignment arc for some job
then we can construct from it an n-cut with the same capacity

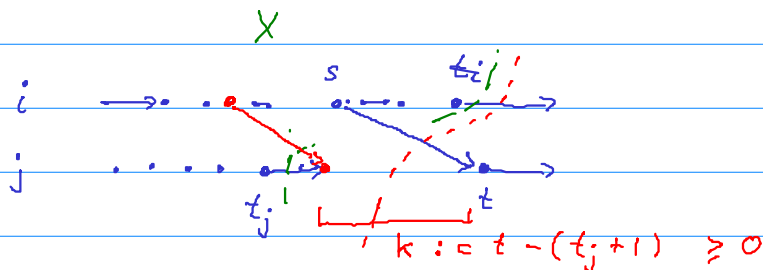
for such jobs let $t_j =$ first index s.t. $v_{jt} \rightarrow v_{j,t+1}$ is forward arc in (X, \bar{X})

define $X^* := \{a\} \cup \bigcup_j \{v_{jt} \mid t \leq t_j\}$ $\bar{X}^* = N \setminus X^*$

(2.1) (X^*, \bar{X}^*) does not contain a temporal arc as forward arc

suppose it does contain $v_{is} \rightarrow v_{jt}$ as forward arc

$\hookrightarrow \hat{=}$ time lag $d_{ij} = t - s$



$$t_j \text{ possible start time} \Rightarrow \boxed{e(j) + 1 \leq t - k} \quad (i)$$

$$\boxed{s - k \leq l(i)} \quad (ii)$$

\uparrow since $s - k \leq s \leq t_j \leq l(i)$

$$\boxed{s-k \geq e(i)+1}$$

(iii)

otherwise $s-k < e(i)+1$

$$\Rightarrow \underline{t-k} = s-k + (t-s) < \underline{e(i) + (t-s) + 1}$$

$$\left. \begin{array}{l} (i,j) \text{ time lag with } d_{ij} = t-s \Rightarrow e(i) + (t-s) \leq e(j) \\ \Rightarrow t-k < e(j)+1, \text{ contradiction to (i)} \end{array} \right\} = 0$$

(iii) $\Rightarrow v_{i,s-k}$ is a start node for i , $v_{i,s-k} \in X^*$ by def of X^*

$$(i) \Rightarrow v_{j,t-k} = v_{j,t+1} \in \bar{X}$$

So the temporal arc $v_{i,s-k} \rightarrow v_{j,t+1}$ is a forward arc of (X, \bar{X})

So $c(X, \bar{X}) = \infty$, a contradiction \Rightarrow (2.1)

(2.2) (X^*, \bar{X}^*) has the same capacity as (X, \bar{X})

clear since (X^*, \bar{X}^*) contains fewer assignment arcs, no temporal arcs, and $w_{jt} \geq 0$

(3) (X^*, \bar{X}^*) can be constructed in poly time from (X, \bar{X})

In $O(nT)$

clear from def of X^*

21.3 Then

There is a one-to-one correspondence between n -cuts of D with finite capacity and feasible solutions of our scheduling problem defined by (1)-(4), namely

$$x_{jt} = \begin{cases} 1 & \text{if } (v_{jt}, v_{j,t+1}) \text{ is in the cut } (X, \bar{X}) \text{ of } D \\ 0 & \text{otherwise} \end{cases}$$

The capacity $c(X, \bar{X})$ is equal to the value $w(x)$ of the scheduling ^{problem}

21A Corollary

The scheduling problem with start-time dependent cost and time lags can be solved by computing a maximum a, b -flow and a corresponding a, b -cut in the digraph D



