

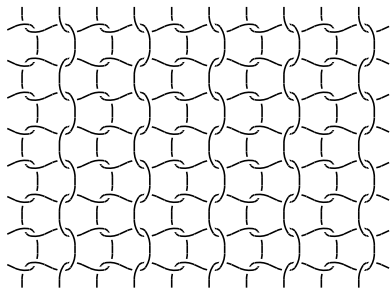
# Knot theory in the thickened torus

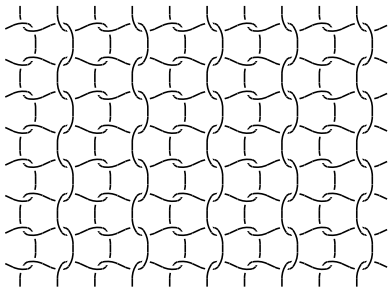
Structures on Surfaces - CIRM 2022

Max Zahoransky von Worlik

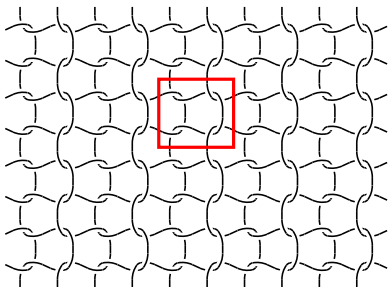


May 2, 2022

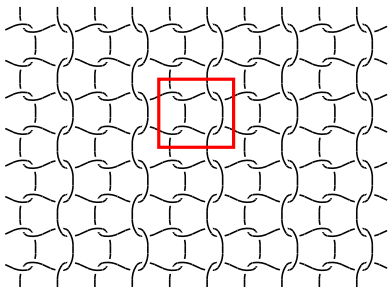




- Goal: distinguish periodic knottings (pictured here: garter stitch)

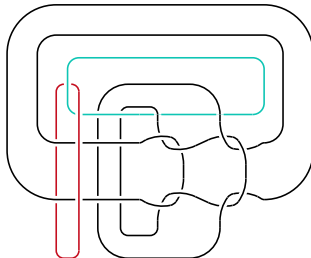


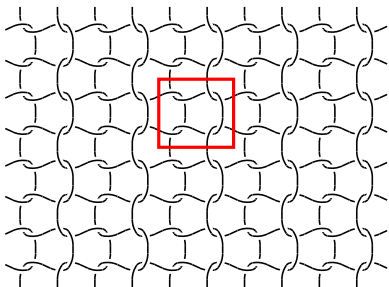
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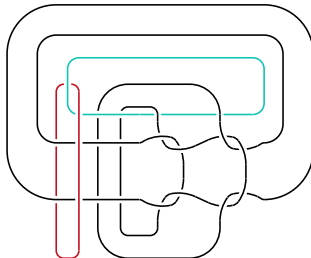
- get a link in  $T^2 \times I$

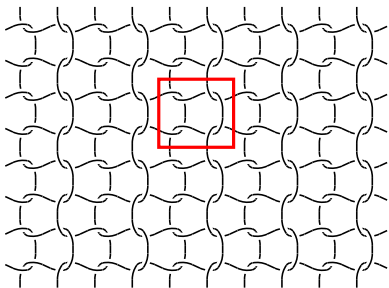




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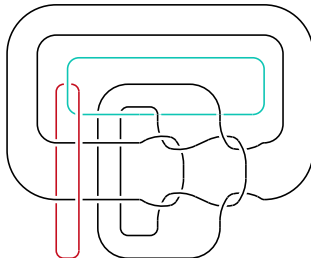
- get a link in  $T^2 \times I$
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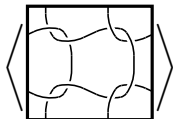


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- get a link in  $T^2 \times I$
- add extra components in the holes
- result: colored link in  $\mathbb{R}^3$  (or  $S^3$ )

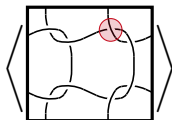


# The Kauffman polynomial





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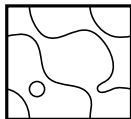
Continue until no crossings are left.

# The Kauffman polynomial

$$\text{Diagram with crossing} = A \cdot \text{Diagram with A-smoothing} + A^{-1} \cdot \text{Diagram with A inverse-smoothing}$$

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What to do with the diagrams without crossings?

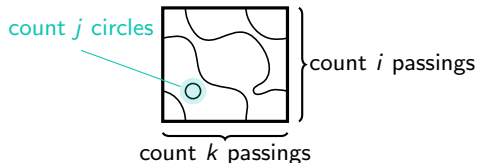


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# The Kauffman polynomial

$$\left\langle \text{link with crossing} \right\rangle = A \left\langle \text{link with A-smoothing} \right\rangle + A^{-1} \left\langle \text{link with A inverse-smoothing} \right\rangle$$

Continue until no crossings are left.

What to do with the diagrams without crossings?

count  $j$  circles

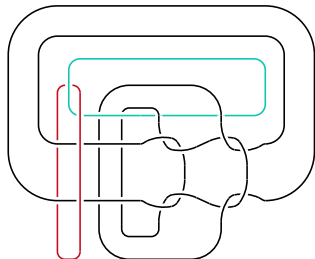
count  $i$  passings

count  $k$  passings

$$\left\langle \text{link with no crossings} \right\rangle = x^k y^i (-A^2 - A^{-2})^j \quad (1)$$

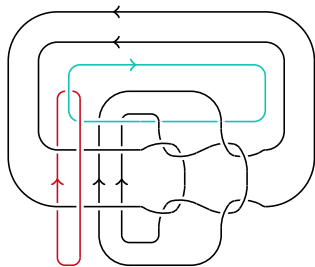
# The Alexander polynomial

- consider augmented link in  $S^3$



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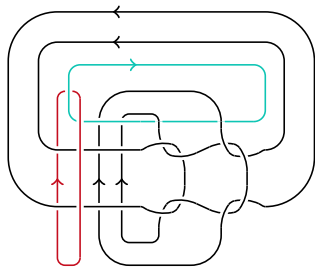
- consider augmented link in  $S^3$
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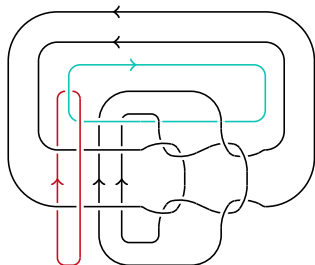


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- choose orientation
- Each crossing gives rise to a row in a matrix  $A(x, y, t)$
- Determinant of the matrix gives a polynomial

$$(x - 1)\Delta_L(x, y, t) = \det A(x, y, t)$$

# Shearing the grid

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In general, shearing is a self-automorphism of the periodic lattice, i.e. an element

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### Theorem

Let  $L$  be a periodic knotting, and  $C(L)$  its image under the linear map  $C$ . Then

$$\langle C(L) \rangle(A, x, y) = \langle L \rangle(A, x^a y^c, x^b y^d)$$

and for some  $k, l \in \mathbb{Z}$ ,

$$\Delta_{C(L)}(x, y, t) = \Delta_L(x^a y^c t^k, x^b y^d t^l, t).$$