

Oriented Matroid

and pseudosphere arrangements

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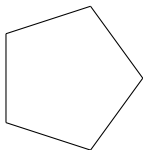
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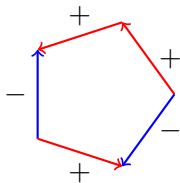
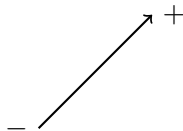
What is an Oriented Matroid?

Matroid Circuits

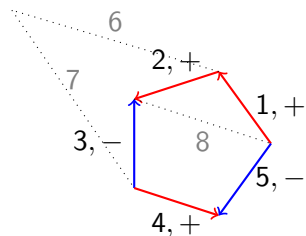


+

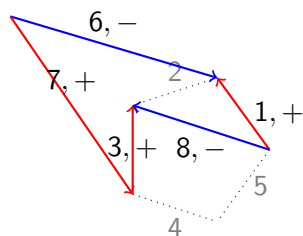
Orientation



What is an Oriented Matroid?

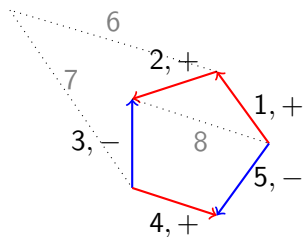


(a) $C = (+, +, -, +, -, 0, 0, 0)$

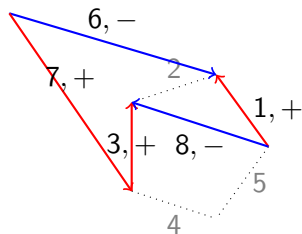


(b) $D = (+, 0, +, 0, 0, -, +, -)$

What is an Oriented Matroid?



(a) $C = (+, +, -, +, -, 0, 0, 0)$



(b) $D = (+, 0, +, 0, 0, -, +, -)$

Composition, Support, and Separation set of covectors

$$(C \circ D)_e := \begin{cases} C_e & \text{if } C_e \neq 0, \\ D_e & \text{otherwise} \end{cases} = (+, +, -, +, -, -, +, -)$$

$$\underline{C} := \{e \in E \mid C_e \neq 0\} = \{1, 2, 3, 4, 5\}$$

$$S(C, D) := \{e \in E \mid C_e = -D_e \neq 0\} = \{3\}$$

Definition of oriented matroid with covector axioms

An **oriented matroid** given in terms of its covectors is a pair $\mathcal{M} := (E, \mathcal{L})$, where $\mathcal{L} \subset \{-, 0, +\}^E$ satisfies

$$(CV0) \quad \mathbf{0} \in \mathcal{L}$$

$$(CV1) \quad C \in \mathcal{L} \implies -C \in \mathcal{L}$$

$$(CV2) \quad C, D \in \mathcal{L} \implies C \circ D \in \mathcal{L}$$

$$(CV3) \quad C, D \in \mathcal{L}, e \in S(C, D) \implies \text{there is a } Z \in \mathcal{L} \text{ with } Z_e = 0 \text{ and with } Z_f = (C \circ D)_f \text{ for } f \in E \setminus S(C, D).$$

Example: Hyperplane Arrangement

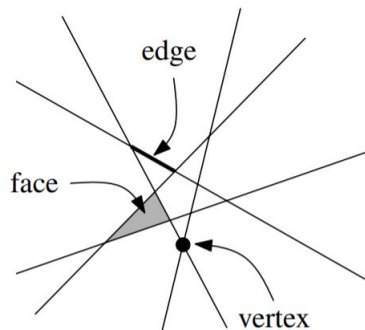


Figure: Line Arrangement[dCvO08]

Example: Hyperplane Arrangement

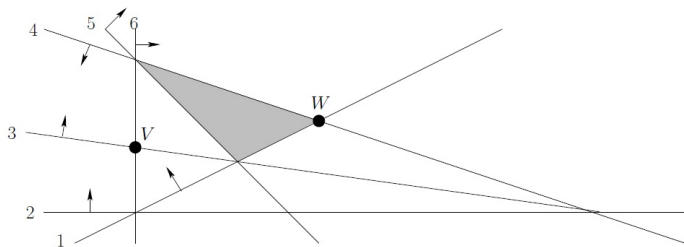


Figure: Oriented hyperplane arrangement[Hoc10]

$$H = \{x \in \mathbb{R}^2 \mid a^T x = c\}$$

$$H^+ = \{x \in \mathbb{R}^2 \mid a^T x > c\}$$

$$H^- = \{x \in \mathbb{R}^2 \mid a^T x < c\}$$

Example: Linear Matroid

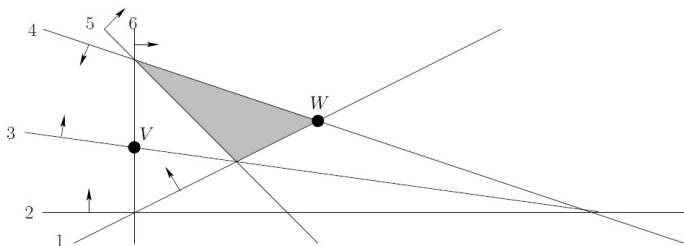


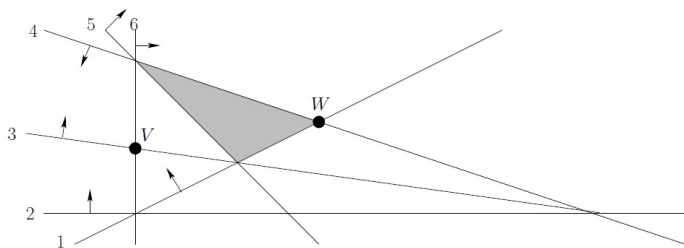
Figure: Oriented hyperplane arrangement[Hoc10]

$$\text{SignVector}(V) = (+ + 0 + - 0)$$

$$\text{SignVector}(W) = (0 + + 0 + +)$$

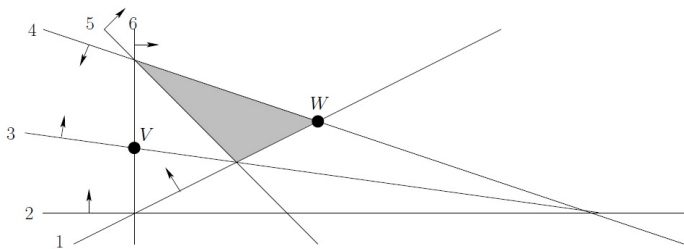
$$\text{SignVector}(\text{Shaded Region}) = (+ + + + + +)$$

Example: Hyperplane Arrangement



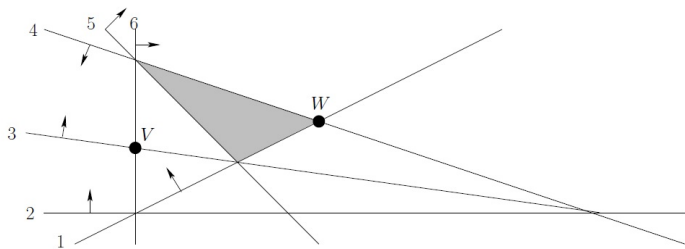
$$\begin{aligned}\mathcal{L} &= \{\pm \text{SignVector}(x) \mid x \in \mathbb{R}^2\} \cup \{\mathbf{0}\} \\ &= \{\pm \text{SignVector}(C) \mid C \text{ cell of the arrangement}\} \cup \{\mathbf{0}\}\end{aligned}$$

Example: Hyperplane Arrangement



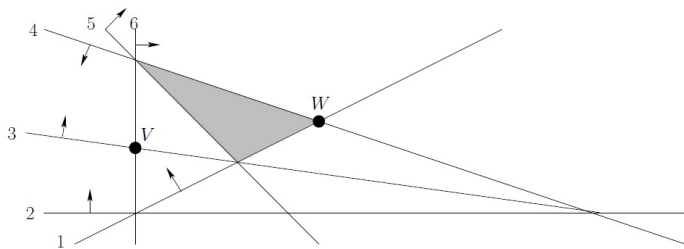
(CV0) $\mathbf{0} \in \mathcal{L}$

Example: Hyperplane Arrangement



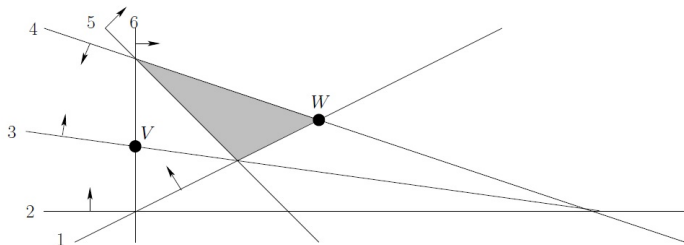
$$(CV1) \quad C \in \mathcal{L} \implies -C \in \mathcal{L}$$

Example: Hyperplane Arrangement



$$(CV2) \quad C, D \in \mathcal{L} \implies C \circ D \in \mathcal{L}$$

Example: Hyperplane Arrangement



(CV3) $C, D \in \mathcal{L}$, $e \in S(C, D) \implies$ there is a $Z \in \mathcal{L}$ with $Z_e = 0$ and with $Z_f = (C \circ D)_f$ for $f \in E \setminus S(C, D)$.

Recall: Cocircuit Axiom

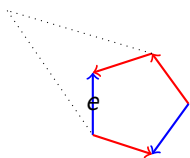
A collection $\mathcal{C}^* \subset \{-, 0, +\}^E$ is the set of cocircuits of an oriented matroid \mathcal{M} if and only if it satisfies

$$(CC0) \quad \mathbf{0} \notin \mathcal{C}^*$$

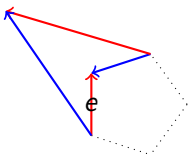
$$(CC1) \quad C \in \mathcal{C}^* \implies -C \in \mathcal{C}^*$$

$$(CC2) \quad \text{for all } C, D \in \mathcal{C}^* \text{ we have } \underline{C} \subset \underline{D} \implies C = D \text{ or } C = -D$$

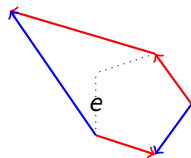
$$(CC3) \quad C, D \in \mathcal{C}^*, C \neq -D, \text{ and } e \in S(C, D) \implies \text{there is a } Z \in \mathcal{C}^* \text{ with } Z^+ \subset (C^+ \cup D^+) \setminus \{e\} \text{ and } Z^- \subset (C^- \cup D^-) \setminus \{e\}$$



(a) C



(b) D



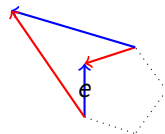
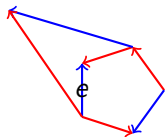
(c) Z

Cocircuit and Covector

Covector C and $e \in C$



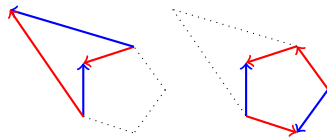
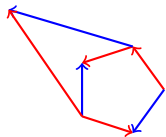
smallest $M \in \mathcal{L}$
s.t. $e \in M \subset C$



Covector C
 $C = M_1 \circ \dots \circ M_m$



Cocircuits M_1, \dots, M_m
 $S(M_i, M_j) = \emptyset$, for $i \neq j$



Example: Linear Matroid

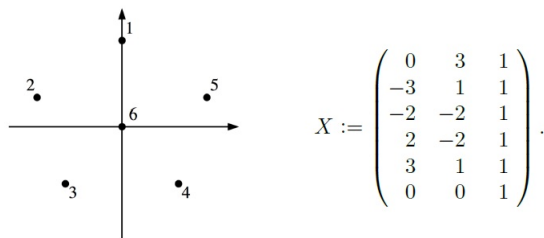


Figure: Homogenized coordinates of points [RZ17]

$$E = \{x_i \mid i = 1, \dots, 6\}$$

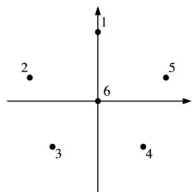
$$\mathcal{I} = \{\text{linearly independent } I \subset E\}$$

$$\mathcal{B} = \{\text{basis } B \subset E \text{ of } \mathbb{R}^d = \mathbb{R}^3\}$$

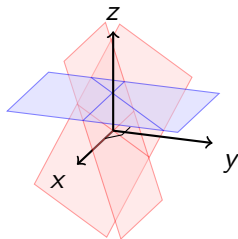
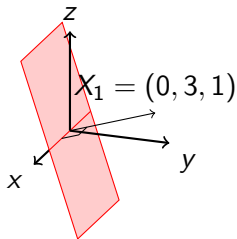
$$\mathcal{C} = \{\text{minimal linearly dependent } S \subset E\}$$

$$\mathcal{C}^* = \{\text{minimal } S \subset E \text{ that intersects each basis}\}$$

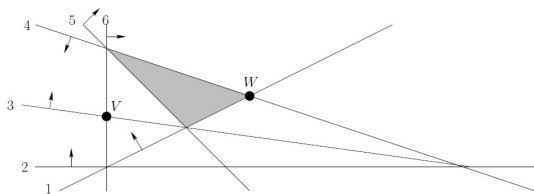
Example: Linear Matroid



$$X := \begin{pmatrix} 0 & 3 & 1 \\ -3 & 1 & 1 \\ -2 & -2 & 1 \\ 2 & -2 & 1 \\ 3 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}.$$



Example: Linear Matroid



$$\begin{aligned} \mathcal{C}^* &= \{\text{minimal } S \subset E \text{ that intersects each basis}\} \\ &= \{\text{minimal } S \subset E \text{ such that } \dim(E \setminus S) < d = 3\} \\ &= \{\text{minimal } S \subset E \mid \dim(E \setminus S) = d - 1 = 2\} \\ &= \{\text{minimal } S \subset E \mid \dim(\text{Ker}(E \setminus S)) = 1\} \\ &= \{S = E \setminus D \mid \text{maximal } D \subset E, \dim(\text{Ker}(D)) = 1\} \\ &= \{S = E \setminus D \mid D = \underline{\text{SignVector}(P)}^0, P \text{ vertex}\} \\ &= \{S = \underline{\text{SignVector}(P)} \mid P \text{ vertex}\} \end{aligned}$$

Example: Linear Matroid

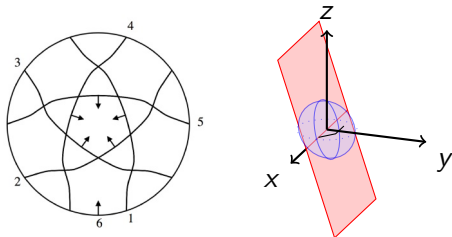


Figure: Hypersphere Arrangement[RZ17] from oriented hyperplanes

What is a Pseudosphere?

A **pseudosphere** is the image $s \subset \mathcal{S}^{d-1}$ of the equator $\{x \in \mathcal{S}^{d-1} \mid x_d = 0\}$ in the unit sphere under a self-homeomorphism $\phi : \mathcal{S}^{d-1} \rightarrow \mathcal{S}^{d-1}$. (Pseudospheres behave “nicely” in the sense that they divide \mathcal{S}^{d-1} into two open sets, its **sides**, that are homeomorphic to open $(d - 1)$ -balls.)

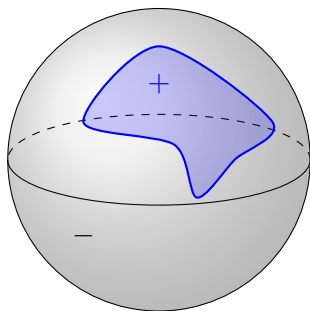
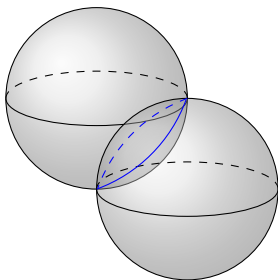


Figure: pseudosphere and its sides, for $d = 3$

What is an Arrangement of Pseudospheres?

A finite collection $\mathcal{P} = (s_1, s_2, \dots, s_n)$ of pseudospheres in \mathcal{S}^{d-1} is an **arrangement of pseudospheres** if the following conditions hold (we set $E := \{1, 2, \dots, n\}$):

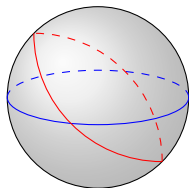
- (PS1) For all $A \subset E$ the set $S_A = \bigcap_{e \in A} s_e$ is a topological sphere.
- (PS2) If $S_A \not\subset s_e$, for $A \subset E$, $e \in E$, then $S_A \cap s_e$ is a pseudosphere in S_A with sides $S_A \cap s_e^+$ and $S_A \cap s_e^-$.



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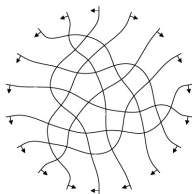


Figure: pseudoline arrangement [RZ17]

Oriented Matroids & Pseudosphere Arrangements

The Topological Representation Theorem

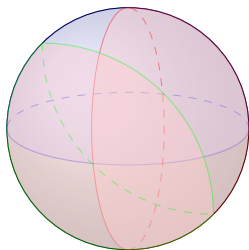
If \mathcal{P} is an essential ($S_E = \emptyset$) arrangement of pseudospheres on S^{d-1} then $\Gamma(\mathcal{P}) \cup \{\mathbf{0}\}$ forms the set of covectors of an oriented matroid of rank d . Conversely, for every oriented matroid (E, \mathcal{L}) of rank d (without loops) there exists an essential arrangement of pseudospheres \mathcal{P} on S^{d-1} with $\Gamma(\mathcal{P}) = \mathcal{L} \setminus \{\mathbf{0}\}$.

$$\left\{ \begin{array}{l} \text{Essential arrangement} \\ \text{of pseudospheres on } S^{d-1} \end{array} \right\} \iff \left\{ \begin{array}{l} \text{Loopless oriented matroid} \\ \text{of rank } d \end{array} \right\}$$

Pseudospheres to Oriented Matroids

$$\left\{ \begin{array}{l} \text{Pseudosphere } s \\ s \subset \mathcal{S}^{d-1} \end{array} \right\} \implies \left\{ \begin{array}{l} \text{Pseudohemispheres} \\ h_s = s^+ \text{ and } -h_s = s^- \end{array} \right\}$$

$\mathcal{C}^* := \{ \text{minimal set } C \neq \emptyset \text{ of pseudohemispheres such that} \\ C \cap -C = \emptyset \text{ and} \\ \cup_{h \in C} h = \mathcal{S}^{d-1} \}$



Oriented Matroids to Pseudospheres

(Induction on $|E|$ for fixed rank d)

- base case: $E = [d]$, $\mathcal{I} = 2^{[d]}$, $\mathcal{C}^* = \{\pm e_i \mid i \in [d]\}$)

$$P_d := \text{Conv}(\{\pm e_1, \dots, \pm e_d\})$$

$$e_i = (0, 0, \dots, 0, 1, 0, \dots, 0)$$

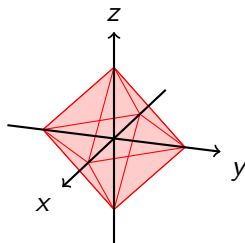


Figure: 3-dimensional Pyramid

\implies Arrangement of ∂P_d

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