

EIGENFUNCTIONS OF THE DIRICHLET AND NEUMANN BOUNDARY VALUE PROBLEMS FOR THE ELLIPTIC SINH-GORDON EQUATION ON A RECTANGLE

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The Dirichlet and Neumann zero boundary value problems on a rectangle for the equation $\Delta u + \sinh u = 0$ are considered. Exact solutions are constructed by means of finite-gap integration theory.

Let R be a rectangular domain, namely,

$$R = \{(x, y) | x \in [0, X], y \in [0, Y]\}.$$

In the present article we construct the solutions of the boundary value problem

$$\begin{cases} \Delta u + \sinh u = 0, & \Delta = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}, \\ u|_{\partial R} = \begin{cases} \mathcal{N} \\ \mathcal{D} \end{cases} \end{cases} \quad (1)$$

$$u|_{\partial R} = \begin{cases} \mathcal{N} \\ \mathcal{D} \end{cases} \quad (2)$$

with Neumann or Dirichlet zero boundary conditions on the edges of R , such that different boundary conditions are admitted on different edges.

This problem arises in the construction of tori with constant mean curvature [1]. Equation (1) is one of the real reductions of the sine-Gordon equation, which is well known in the theory of solitons. Finite-gap solutions of the latter equation, which were first constructed in [2], can be used to solve the problem (1), (2).

We consider the Riemann surface G of genus g of the hyperbolic curve

$$\mu^2 = \lambda \prod_{i=1}^g (\lambda - c_i) (\lambda - 1/\bar{c}_i), \quad |c_i| \neq 1. \quad (3)$$

The surface consists of two copies of the complex plane pasted together along the cuts $[0, \infty]$ and $[c_i, 1/\bar{c}_i]$. We take a contour $\mathcal{L}$ on G that encompasses the cut $[0, \infty]$, and we choose a canonical basis of cycles on G in such a way that a_i encompasses the cut $[c_i, 1/\bar{c}_i]$ and $\mathcal{L} = a_1 + a_2 + \dots + a_g$. We fix a branch of the function $\sqrt{\lambda}$ on $G \setminus \mathcal{L}$. $U = (U_1, \dots, U_g)$ and $V = (V_1, \dots, V_g)$, where

$$U_n = \int_{b_n} d\Omega_1, \quad V_n = \int_{b_n} d\Omega_2$$

are the vectors formed by the b -periods of the normalized Abelian differentials of the second kind with singularities of the form

$$d\Omega_1 = d(\sqrt{\lambda}), \quad \lambda \sim \infty, \quad d\Omega_2 = d(1/\sqrt{\lambda}), \quad \lambda \sim 0.$$

du_n denote holomorphic differentials normalized in the chosen basis in such a way that $\int_{a_n} du_m = 2\pi i \delta_{nm}$, and $B_{nm} = \int_{a_n} du_m$ is the matrix of periods, which determines the corresponding Riemann theta function

$$\theta(p) = \sum_{k \in \mathbb{Z}^g} \exp \left(\frac{1}{2} (Bk, k) + (p, k) \right), \quad p = (p_1, \dots, p_g) \in \mathbb{C}^g.$$

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For the curve (3) there is the antiholomorphic involution $\tau: \lambda \rightarrow 1/\bar{\lambda}$, the action of which generates the following transformations:

$$\tau a_n = -a_n, \quad \tau b_n = b_n - a_n + \sum_{i=1}^g a_i, \quad \tau \sqrt{\lambda} = \frac{1}{\sqrt{\lambda}}, \quad \tau^* d\Omega_1 = \overline{d\Omega_2}, \quad (4)$$

from which it follows that $\bar{U} = V$.

THEOREM (3). All real-valued finite-gap solutions of Eq. (1) are given by the formula

$$u(x, y) = \ln \left(\frac{\theta(\Omega + D)}{\theta(\Omega + D + \Delta)} \right)^2, \quad \Omega = \frac{i}{2}(\alpha x - \beta y), \quad (5)$$

$$\Delta = \pi i(1, 1, \dots, 1), \quad iD \in \mathbb{R}^g, \quad U = \alpha + i\beta, \quad \alpha, \beta \in \mathbb{R}^g,$$

where $\theta(p)$ is the theta function of the curve (3) and D is an arbitrary vector. All of the solutions are nonsingular.

Let now $\pi: \lambda \rightarrow 1/\lambda$ be an involution of G . It is not difficult to show that the basis of cycles on G can be chosen in such a way that, apart from (4), it also undergoes the transformations

$$\pi a = a\Pi, \quad \pi b = b\Pi, \quad \Pi = \begin{pmatrix} 0 & \dots & 0 & 1 \\ 0 & \dots & 1 & 0 \\ \vdots & & \vdots & \vdots \\ 1 & \dots & 0 & 0 \end{pmatrix}, \quad a = (a_1, \dots, a_g), \quad b = (b_1, \dots, b_g) \quad (6)$$

under the action of π . Since $\pi^* \sqrt{\lambda} = -1/\sqrt{\lambda}$, the Abelian differentials of the second kind are transformed into each other under the action of π :

$$\pi^* d\Omega_1 = -d\Omega_2. \quad (7)$$

In turn, equalities (6) and (7) ensure that the following symmetry properties hold for the theta function and the vectors α and β :

$$\theta(p) = \theta(p\Pi) = \theta(-p\Pi), \quad \alpha = -\alpha\Pi, \quad \beta = \beta\Pi. \quad (8)$$

Let us note that all the arguments of the theta function in (5) are purely imaginary. The theta function is periodic with periods $2\pi i N$, where N is a g -dimensional vector with integral entries. Equality to within such periods will be written in the following way:

$$z_1 \equiv z_2 \iff z_1 = z_2 + 2\pi i N, \quad N \in \mathbb{Z}^g.$$

LEMMA. If $D \equiv D\Pi$, then $u(-x, y) = u(x, y)$.
If $D \equiv D\Pi + \Delta$, then $u(-x, y) = -u(x, y)$.
If $D \equiv -D\Pi$, then $u(x, -y) = u(x, y)$.
If $D \equiv -D\Pi + \Delta$, then $u(x, -y) = -u(x, y)$.

This assertion is a direct consequence of (8) and the fact that $\Delta \equiv \Delta\Pi \equiv -\Delta\Pi$. Using this assertion one can easily prove the following result.

THEOREM. The solution (5) of Eq. (1) constructed from the Riemann surface G with the involution π satisfies the Dirichlet ($\mathcal{D}$) or Neumann ($\mathcal{N}$) zero boundary conditions on the edges of R if the following conditions are satisfied:

∂R	$\mathcal{N}$	$\mathcal{D}$
$x = 0$	$D \equiv D\Pi$	$D \equiv D\Pi + \Delta$
$y = 0$	$D \equiv -D\Pi$	$D \equiv -D\Pi + \Delta$
$x = X$	$\alpha X \equiv D\Pi - D$	$\alpha X \equiv D\Pi - D + \Delta$
$y = Y$	$\beta Y \equiv D\Pi + D$	$\beta Y \equiv D\Pi + D + \Delta$

In particular, if the Neumann zero boundary conditions are satisfied on the entire boundary ∂R , then we get $\alpha X \equiv \beta Y \equiv 0$, $D \equiv \pi i(\varepsilon, \varepsilon)$ if $g = 2k$, and $D \equiv \pi i(\varepsilon, \varepsilon + 1)$, where $\varepsilon = (\varepsilon_1, \dots, \varepsilon_k)$ with $\varepsilon_i \in \{0, 1\}$. If the condition $u|_{\partial R} = 0$ holds, we have $g = 2k$, $\alpha X \equiv \beta Y \equiv 0$, and $D \equiv \pi i(\varepsilon, \varepsilon) + (1, 0)$, where $\mathbf{1}$ is a k -dimensional row whose entries are equal to 1.

By virtue of (8), the equalities $\alpha X \equiv \beta Y \equiv 0$ represent g conditions for g free parameters (branching points) of the Riemann surface C .

The curve C is a two-sheeted covering of C/π . Using the reduction technique for theta functions [4], one can easily show that the original g -dimensional theta function can be expressed in terms of the product of two theta functions of dimension $k+1$ and k if $g = 2k+1$, or k and k if $g = 2k$ in such a way that the variables x and y are separated, i.e., they appear in the arguments of different theta functions.

It turns out that we have constructed all solutions of the boundary value problems posed. This fact can be proved with the aid of the following important theorem.

THEOREM. All double-periodic nonsingular solutions of Eq. (1) are finite-gap solutions.

PROOF: We denote by Λ the lattice of periods of the solution $u(x, y)$. We "include" the "higher" flows of Eq. (1). In this case u depends on infinitely many "higher" times t_k and $u(x, y, t_1, t_2, \dots)$ as a function of x and y satisfies Eq. (1) as before. We have

$$(\Delta + \cosh u)u_k = 0 \quad (9)$$

for all partial derivatives u_k . Since (9) is an operator on the torus $\mathbb{R}^2/\Lambda$, it has a finite-dimensional kernel. It follows that u_k are linearly dependent and there exists a "higher" time t with respect to which the solution is stationary, i.e. $u_t = 0$, which proves that u is a finite-gap solution.

Final remarks:

1. Finite-gap solutions of a boundary value problem were first constructed in [5] for the nonlinear Schrödinger equation on an interval with a general boundary condition.
2. In analogy with the case considered, one can construct all the solutions of the Dirichlet and Neumann problems on a rectangle with zero boundary conditions for other elliptic equations with important physical applications, namely, the real reductions $\Delta u = \sin u$, $\Delta u = \sinh u$, and $\Delta u = \cosh u$ of the sine-Gordon equation.

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DIFFRACTION OF ELASTIC WAVES BY A FREE WEDGE. REDUCTION TO A SINGULAR INTEGRAL EQUATION

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The problem of diffraction of a plane elastic wave by a free wedge is considered. A method of reduction of the problem to a singular integral equation is proposed.

Although there is a very large bibliography devoted to the problem of diffraction of elastic waves by a free wedge, a satisfactory approach to the problem has not been found so far. In the present article a method of reduction of the problem of diffraction of a plane wave to a certain integral equation on an open contour is proposed. In degenerated cases (diffraction by a slit and reflection off a plane) the equation is also degenerated and can be solved by quadratures. In cases that are close to the degenerated ones the solution of the equation can be constructed in the form of Neumann's series. In the general case one can use numerical methods, which are very well developed for the type of equations in question.

As far as the problem as a whole is concerned, it can be included in the category of "computational" problems in the sense that the qualitative picture of the wave field is obvious and the gist of the problem consists in determining the quantitative characteristics rather than the structural features of the field. From this point of view, the reduction of the problem of diffraction to a singular integral equation is in full agreement with the essence of the problem, since it brings to light the underlying method for computing the quantities that are of interest.

It is necessary to remark that only the general scheme of the method is presented in this article. A detailed description of the method and the proofs of the assertions stated were published in [1].

1. Formulation of the problem. We consider a homogeneous isotropic elastic medium that occupies the wedge-shaped domain $\Gamma = \{\rho \geq 0, |\theta| \leq \alpha\}$ defined in a polar system of coordinates $\{\rho, \theta\}$. The properties of the medium are determined by the Lamé constants λ and μ , and its motion can be described in terms of the longitudinal and transversal potentials $\varphi(\rho, \theta)$ and $\psi(\rho, \theta)$ satisfying the Helmholtz equations

$$\nabla^2 \varphi + \gamma^2 k^2 \varphi = 0, \quad \nabla^2 \psi + k^2 \psi = 0, \quad (1.1)$$

which depend on the wave number k and the ratio

$$\gamma = \frac{v_s}{v_p} = \sqrt{\frac{\lambda}{\lambda + 2\mu}} < 1 \quad (1.2)$$

of the speeds of propagation of transversal (v_s) and longitudinal (v_p) waves.

It is assumed that the density of the energy of the elastic medium satisfies the local integrability condition, which can be formulated as the requirement that the displacements

$$u = \frac{\partial \varphi}{\partial \rho} + \frac{1}{\rho} \frac{\partial \psi}{\partial \theta}, \quad v = \frac{\partial \psi}{\partial \rho} + \frac{1}{\rho} \frac{\partial \varphi}{\partial \theta} \quad (1.3)$$

exhibit the following asymptotic behaviour as $\rho \rightarrow 0$:

$$u = O(\rho^p), \quad v = O(\rho^p), \quad \text{Re } p \leq 0, \quad \rho \rightarrow 0. \quad (1.4)$$

The boundaries $\theta = \pm \alpha$ of Γ are assumed to be free of stresses, i.e., the following conditions are imposed on the potentials $\varphi(\rho, \theta)$ and $\psi(\rho, \theta)$:

$$t_{\rho\theta}[\varphi, \psi](\rho, \pm \alpha) = t_{\theta\theta}[\varphi, \psi](\rho, \pm \alpha) = 0, \quad (1.5)$$

where

$$\begin{cases} \frac{1}{\mu} t_{\rho\theta} = \frac{1}{\rho} \frac{\partial u}{\partial \theta} + \frac{\partial v}{\partial \rho} - \frac{v}{\rho}, \\ \frac{1}{\mu} t_{\theta\theta} = \frac{1}{\gamma^2} \left[\frac{1}{\rho} \frac{\partial v}{\partial \theta} + \frac{\partial u}{\partial \rho} + \frac{u}{\rho} \right] - 2 \frac{\partial u}{\partial \rho}. \end{cases} \quad (1.6)$$

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