

2. Exercise sheet - solutions

FV/FD-Methods for the solution of pde's

Discussion: 12.6.15-16.6.16

1) Exercise

Show the benefit of the Kronecker product of matrices to implement a coefficient/stiffness matrix for the Poisson problems of the exercises of exercise sheet Nr. 1.

2) Exercise

Solve the equation

$$-u_{xx} - u_{yy} = (2 - \sqrt{x^2 + y^2})(1 - \sqrt{x^2 + y^2})y/\sqrt{x^2 + y^2}.$$

on

$$\Omega = \{(x, y) \mid 1 < x^2 + y^2 < 4\}$$

with homogeneous boundary conditions.

Solution:

There is a possibility to use an Ansatz

$$U(r, \varphi) = R(r) \sin \varphi.$$

For $R(r)$ the equation

$$-\frac{1}{r} \frac{\partial}{\partial r} \left[r \frac{\partial R}{\partial r} \right] + \frac{1}{r^2} R = r^2 - 3r + 2$$

is to solve. This is possible with the Ansatz

$$R(r) = p_4(r) + w(r),$$

where p_4 is a polynomial of 4th order and w is a solution of

$$-\frac{1}{r} \frac{\partial}{\partial r} \left[r \frac{\partial w}{\partial r} \right] + \frac{1}{r^2} w = 0.$$

The other way is to solve the problem numerically on an annulus circular ring with a periodicity in the φ -direction.

Listing 1: source code

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1 % Exercise 3 problem 1
2 %
3 % Berechnung der Temperaturverteilung auf einer Kreisscheibe
4 % \Omega = \{ 1 < x^2 + y^2 < 4 \}
5 % -\div ( \lambda \grad T ) = f in \Omega, T = 0 auf \partial \Omega,
6 % f(x,y) = 1 in \Omega_0 = \{ (x-2)^2 + (y-2)^2 <= 1/4 \}, sonst =0
7 % \lambda = 1
8 n = 30;
9 m = 40;

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10 R0 = 1.;
11 R1 = 2.;
12 drho = (R1-R0)/n;
13 dphi = 2*pi/m;
14 % Zentralpunkte der Finiten Zellen
15 rho = linspace(R0+drho/2,R1-drho/2,n);
16 for i=1:n
17     invrho(i) = 1/rho(i);
18 end
19 phi = linspace(0+dphi/2,2*pi-dphi/2,m);
20 % Randpunkte der Finiten Zellen
21 rhop = linspace(R0,R1,n+1);
22 phip = linspace(0,2*pi,m+1);
23 % Matrixaufbau Ar
24 Ar = zeros(n,n);
25 for i=1:n
26     if (i == 1)
27         Ar(i,i) = rhop(1)+rhop(2);
28         Ar(i,i+1) = -rhop(1);
29     elseif (i == n)
30         Ar(i,i) = rhop(n-1)+rhop(n);
31         Ar(i,i-1) = -rhop(n-1);
32     elseif (i > 1 && i < n)
33         Ar(i,i) = rhop(i-1) + rhop(i);
34         Ar(i,i-1) = -rhop(i-1);
35         Ar(i,i+1) = -rhop(i);
36     end
37 end
38 % Matrixaufbau Aphi
39 Aphi = zeros(m,m);
40 for j= 1:m
41     if (j == 1)
42         Aphi(1,1) = 2;
43         Aphi(1,2) = -1;
44         Aphi(1,m) = -1;
45     elseif (j == m)
46         Aphi(m,m) = 2;
47         Aphi(m,m-1) = -1;
48         Aphi(m,1) = -1;
49     elseif (j > 1 && j < m)
50         Aphi(j,j) = 2;
51         Aphi(j,j+1) = -1;
52         Aphi(j,j-1) = -1;
53     end
54 end
55 Irho = drho*eye(n);
56 Iphi = dphi*eye(m);
57 % Steifigkeitsmatrix
58 AA = kron(Iphi,Ar) + kron(Aphi,diag(invrho)*Irho);
59 % rechte Seite (Faktor r*drho*dphi, und Dimension)
60 R = kron(Iphi*ones(m,1),diag(rho)*Irho*ones(n,1));
61 %
62 % rechte Seite (Beruecksichtigung des Quellglieds)
63 for j=1:m
64     for i=1:n
65         ind = i + (j-1)*n;
66         f(ind) = (2-rho(i))*(1-rho(i))*sin(phi(j));
67         R(ind) = R(ind)*f(ind);
68     end
69 end
70 %
71 U = AA\R;
72 %
73 %
74 % reshape
75 % Vektor U ==> Matrix X
76 X = reshape(U,n,m);
77 % Plot
78 for i=1:n
79     for j=1:m
80         xk(i,j) = rho(i)*cos(phi(j));

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81     yk(i,j) = rho(i)*sin(phi(j));
82 end
83 xk(i,m+1) = xk(i,1);
84 yk(i,m+1) = yk(i,1);
85 end
86 XP = [X, X(:,1)];
87 figure(1);
88 mesh(xk,yk,XP)
89 title('u-Feld durch Sinus-Quelle erzeugt')
90 xlabel('u(\rho,\phi)')

```

3) Exercise

Solve the steady state heat conduction boundary value problem

$$\begin{aligned}
 -\Delta u &= 0, & \text{in } \Omega &= \{(x,y,z) | x^2 + y^2 < 1, 0 < z < 2\} \\
 u &= 1, & \text{on } \Gamma_1 &= \{(x,y,0) | x^2 + y^2 < 1\} \\
 \frac{\partial u}{\partial n} &= 0, & \text{on } \Gamma_2 &= \{(x,y,z) | x^2 + y^2 = 1, 0 < z < 2\} \\
 \frac{\partial u}{\partial n} &= 1, & \text{on } \Gamma_3 &= \{(x,y,2) | x^2 + y^2 < 1\}.
 \end{aligned}$$

$\frac{\partial}{\partial n}$ means the outer normal directional derivative on Γ .

Solution:

This problem has a trivial solution $u(r,z) = z + 1$.

The numerical solution is a good test for the implementation of a FD/FV-method for more complicated boundary conditions and source terms.

The way to solve the problem numerically with a finite difference scheme is a problem formulation in cylindrical coordinates. It is important to note that there is no dependence of φ and though we can solve the problem in the 2d rectangle

$$\hat{\Omega} = \{(r,z) \in [0,1] \times [0,2]\}.$$

The following listing contains a program of an implemented Finite-Volume method.

Listing 2: source code

```

1 % Exercise 3, problem 2
2 %
3 %
4 % Berechnung der Temperaturverteilung in einem Zylinder
5 % \Omega = \{ 0 < x^2 + y^2 < 4, 0 < z < 2 \}
6 % -\div(\grad T) = 0 in \Omega, RB siehe Uebungsblatt
7 % Waermequelle in einem Zylinderring \{ r3^2 < x^2 + y^2 < r4^2, 0 < z < 2 \}
8 n = 20;
9 m = 30;
10 R0 = 0.;
11 R1 = 1.;
12 z0 = 0;
13 z1 = 2;
14 drho = (R1-R0)/n;
15 dz = (z1-z0)/m;
16 % Zentralpunkte der Finiten Zellen
17 rho = linspace(R0+drho/2,R1-drho/2,n);
18 for i=1:n
19     invrho(i) = 1/rho(i);
20 end
21 z = linspace(z0+dz/2,z1-dz/2,m);
22 % Randpunkte der Finiten Zellen
23 rhop = linspace(R0,R1,n+1);
24 zp = linspace(z0,z1,m+1);
25 % Matrixaufbau Ar
26 Ar = zeros(n,n);

```

```

27 for i=1:n
28     if (i == 1)
29         Ar(i,i) = rhop(2);
30         Ar(i,i+1) = -rhop(2);
31     elseif (i == n)
32         Ar(i,i) = rhop(n-1);
33         Ar(i,i-1) = -rhop(n-1);
34     elseif (i > 1 && i < n)
35         Ar(i,i) = rhop(i-1) + rhop(i);
36         Ar(i,i-1) = -rhop(i-1);
37         Ar(i,i+1) = -rhop(i);
38     end
39 end
40 % Matrixaufbau Az
41 Az = zeros(m,m);
42 for j= 1:m
43     if (j == 1)
44         Az(1,1) = 3;
45         Az(1,2) = -1;
46     elseif (j == m)
47         Az(m,m) = 1;
48         Az(m,m-1) = -1;
49     elseif (j > 1 && j < m)
50         Az(j,j) = 2;
51         Az(j,j+1) = -1;
52         Az(j,j-1) = -1;
53     end
54 end
55 Irho = drho*eye(n);
56 Iz = dz*eye(m);
57 % Steifigkeitsmatrix
58 AA = kron(Iz,Ar) + kron(Az,diag(rho))*Irho;
59 % rechte Seite (Faktor r*drho*dz, und Dimension)
60 R = kron(Iz*ones(m,1),diag(rho))*Irho*ones(n,1);
61 %
62 % rechte Seite (Beruecksichtigung des Quellglieds)
63 for j=1:m
64     for i=1:n
65         ind = i + (j-1)*n;
66     % keine Waermequelle
67         f(ind) = 0;
68         fr(ind) = 0;
69     % Randbedingungen
70         if (j == 1)
71             fr(ind) = drho*rho(i)*2;
72         elseif (j == m)
73             fr(ind) = drho*rho(i)*1*dz;
74         end
75         R(ind) = R(ind)*f(ind) + fr(ind);
76     end
77 end
78 %
79 U = AA\R;
80 %
81 % reshape
82 X = reshape(U,n,m);
83 % exakte Loesung
84 for i=1:n
85     for j=1:m
86         UE(i,j) = z(j)+1;
87     end
88 end
89 % Fehler
90 err = norm(X-UE)
91 % Plot
92 for i=1:n
93     for j=1:m
94         xk(i,j) = rho(i);
95         yk(i,j) = z(j);
96     end
97 end

```

```

98 figure(1);
99 mesh(xk,yk,X)
100 title('u-Feld_Zylinderschnitt')
101 xlabel('u(\rho,z)')

```

4) Exercise

Construct the mapping $\Psi : \{1, 2, \dots, N\} \times \{1, 2, \dots, M\} \rightarrow \{1, 2, \dots, N * M\}$ which maps the position (i, j) of a rectangular matrix A of type $N \times M$ to the relevant index ind of a vector $\vec{a} \in \mathbb{R}^{N \times M}$ which contains row by row of A , and its inverse Ψ^{-1} .

Solution:

Listing 3: source code

```

1 % exercise 3.3a
2 %
3 function ind = index_gb(i,j,n,m)
4
5 % n Zeilenzahl
6 % m Spaltenzahl
7 % (i,j) -> ind
8
9 ind = j + (i-1)*m;

```

Listing 4: source code

```

1 % exercise 3.3b
2 %
3 function [i,j] = invindex_gb(ind,n,m)
4
5 % n Zeilenzahl
6 % m Spaltenzahl
7 % ind -> (i,j)
8
9 if floor(ind/m)*m == ind
10 i=ind/m; j = m;
11 else
12 i = floor(ind/m)+1; j = ind - (i-1)*m;
13 end

```

5) Exercise

The 2d coefficient matrix A of the Poisson problem $-\Delta u = f$ on a quadratic domain Ω with Dirichlet boundary conditions we can create using the Kronecker-product

$$A_2 = I \otimes A + A \otimes I$$

with $A \in \mathbb{R}^{(N-1) \times (N-1)}$

$$A = \begin{pmatrix} 2 & -1 & 0 & 0 & \dots & 0 \\ -1 & 2 & -1 & 0 & \dots & 0 \\ & & & \ddots & & \\ 0 & \dots & 0 & -1 & 2 & -1 \\ 0 & \dots & 0 & 0 & -1 & 2 \end{pmatrix}$$

and the identity $I \in \mathbb{R}^{(N-1) \times (N-1)}$.

Show the formula

$$(C \otimes B)(v \otimes w) = Cv \otimes Bw$$

and use it to determine the eigenvalues of A_2 when A has the eigenvalues $\lambda_1, \dots, \lambda_{N-1}$.
 Solution:

For

$$C = (c_{ij})_{\substack{i=1,\dots,N \\ j=1,\dots,M}} \quad \text{and} \quad B \in \mathbb{R}^{P \times K}$$

we get

$$C \otimes B = (c_{ij}B)_{\substack{i=1,\dots,N \\ j=1,\dots,M}} \in \mathbb{R}^{NM \times NM}.$$

Be that

$$v = [v_1 \ v_2 \ \dots \ v_M]^T, \quad w \in \mathbb{R}^K$$

than we have

$$v \otimes w = (v_i w)_{i=1,\dots,M} = \begin{pmatrix} v_1 w \\ v_2 w \\ \vdots \\ v_M w \end{pmatrix} \in \mathbb{R}^{MK}.$$

With the Einstein-sum-convention $(Cv)_i = c_{ij}v_j \ \forall i = 1, \dots, N$ we get

$$\begin{aligned} Cv \otimes Bw &= (Cv)_i Bw \\ &= c_{ij}v_j Bw = c_{ij}Bv_j w \\ &= (C \otimes B)(v \otimes w). \end{aligned}$$

The second part of this exercise is trivial by using the Eigenvektors u_l of A and the application of the proved rule to

$$A_2(u_l \otimes u_s) = [I \otimes A + A \otimes I](u_l \otimes u_s).$$