TECHNISCHE UNIVERSITÄT BERLIN Institut für Mathematik

Prof. Dr. John M. Sullivan **Geometry I** WS 09/10 Dott. Matteo Petrera http://www.math.tu-berlin.de/~sullivan/L/09W/Geo1/

Exercise Sheet 5

Exercise 1: Circles.

Let C denote the Euclidean circle with center (0, s) and radius s, where 0 < s < 1/2.

- 1. Compute the center and radius of the hyperbolic circle represented by C in the Poincaré disk model \mathbb{D}^2 .
- 2. Let C' denote the hyperbolic circle in \mathbb{D}^2 with center (0,0) and the same hyperbolic radius as C. Then as Euclidean circles, which has larger radius, C or C'? Why?

Exercise 2: Möbius transformations.

Consider the half-plane model $\mathbb{H}^2_+ := \{z \in \mathbb{C} \mid \text{Im}(z) > 0\}$. Let $C \subset \mathbb{H}^2_+$ be a hyperbolic line (i.e. either a semicircle orthogonal to the real axis or a vertical straight line). Let γ be a Möbius transformation defined by

$$\gamma(z) := \frac{az+b}{cz+d}, \qquad a,b,c,d \in \mathbb{R}, \ ad-bc > 0.$$

- 1. Prove that $\gamma(C)$ is a hyperbolic line.
- 2. Let $C' \neq C$ be a hyperbolic line. Prove that there exists a Möbius transformation that maps C to C'.

Exercise 3: Projective lines in $P^2(\mathbb{R})$ **.**

- 1. Find the equation of the projective line in $P^2(\mathbb{R})$ joining A = [1, 2, 0] to B = [1, 0, 1].
- 2. Let $\ell \subset P^2(\mathbb{R})$ be the projective line through [0, 1, 1] and [1, 0, 1]; let $\ell' \subset P^2(\mathbb{R})$ be the projective line through [1, 1, 1] and [0, 2, -1]. Find the homogeneous coordinates of the point $\ell \cap \ell'$.

Exercise 4: Projective transformations in $P^2(\mathbb{R})$ **.**

1. Find a projective transformation $\tau_1: P^2(\mathbb{R}) \to P^2(\mathbb{R})$ which maps the points

$$P_0 = [1, 2, 0], \quad P_1 = [0, 1, 0], \quad P_2 = [-1, 0, 2], \quad P_3 = [-1, 3, 4],$$

to the points

$$Q_0 = [1, 0, 0], \quad Q_1 = [1, 1, 0], \quad Q_2 = [0, -1, 1], \quad Q_3 = [1, 1, 1],$$

respectively.



(4 pts)

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2. Find a projective transformation $\tau_2 : P^2(\mathbb{R}) \to P^2(\mathbb{R})$ which maps the points P_0, P_1, P_2, P_3 from 1. to the points P_3, P_2, P_1, P_0 (i.e. τ_2 interchanges these points).

Exercise 5 (optional): Riemannian metrics.

(extra 4 pts)

Consider the following hyperbolic models:

$$\mathbb{J} := \{ (x_1, \dots, x_{n+1}) \, | \, x_1^2 + \dots + x_{n+1}^2 = 1, \, x_{n+1} > 0 \}, \\ \mathbb{L} := \{ (x_1, \dots, x_{n+1}) \, | \, x_1^2 + \dots + x_n^2 - x_{n+1}^2 = -1, \, x_{n+1} > 0 \}.$$

 $\mathbb J$ is the Hemisphere model and $\mathbb L$ is the Hyperboloid model. The corresponding Riemannian metrics are:

$$ds_{\mathbb{J}}^{2} = \frac{dx_{1}^{2} + \dots + dx_{n+1}^{2}}{x_{n+1}^{2}}, \qquad ds_{\mathbb{L}}^{2} = dx_{1}^{2} + \dots + dx_{n}^{2} - dx_{n+1}^{2}.$$

The isometry between \mathbb{L} and \mathbb{J} is the central projection from the point $(0, 0, \dots, 0, -1)$:

$$\alpha : \mathbb{L} \to \mathbb{J}, \quad (x_1, \dots, x_{n+1}) \mapsto \left(\frac{x_1}{x_{n+1}}, \dots, \frac{x_n}{x_{n+1}}, \frac{1}{x_{n+1}}\right).$$

Prove that $\alpha^*(ds_{\mathbb{J}}^2) = ds_{\mathbb{L}}^2$, where $\alpha^*(ds_{\mathbb{J}}^2)$ is the pullback of $ds_{\mathbb{J}}^2$ by the isometry α .