

Exercise Sheet 3

Exercise 1: Hyperbolic circles. (4 pts)

Define the circle of radius r around point $c \in \mathbb{H}^2$ as

$$C_r(c) := \{x \in \mathbb{H}^2 \mid d(c, x) = r\},$$

where $d(\cdot, \cdot)$ denotes the hyperbolic distance. Find the length of $C_r(c)$. (Hint: It is enough to consider circles with center $(0, 0, 1)$. Why?)

Exercise 2: Orthogonal lines. (4 pts)

Let l_1 and l_2 be hyperbolic lines with unit normals n_1 and n_2 . Show that there exists a unique hyperbolic line l_3 such that $l_1 \perp l_3$ and $l_2 \perp l_3$ if and only if $|\langle n_1, n_2 \rangle| > 1$.

Exercise 3: Hyperbolic triangles. (4 pts)

Consider an hyperbolic triangle with sidelengths a, b, c and interior angles α, β, γ .

1. Prove the hyperbolic angle cosine theorem:

$$\cosh a = \frac{\cos \alpha + \cos \beta \cos \gamma}{\sin \beta \sin \gamma}.$$

2. Assume that $\gamma = \pi/2$. Prove the following formulas:

$$\begin{aligned} \cosh c &= \cosh a \cosh b, & (\text{Pythagorean theorem}) \\ \sin \alpha &= \frac{\sinh a}{\sinh c}. \end{aligned}$$

Exercise 4: Scalar products. (6 pts)

- Let $\text{Mat}_{m \times n}(\mathbb{R})$ be the space of $m \times n$ real matrices. By using the isomorphism $\text{Mat}_{m \times n}(\mathbb{R}) \simeq \mathbb{R}^{mn}$ prove that the Euclidean scalar product on \mathbb{R}^{mn} induces a scalar product on $\text{Mat}_{m \times n}(\mathbb{R})$ given by $\langle A, B \rangle = \text{trace}(A^T B)$, $A, B \in \text{Mat}_{m \times n}(\mathbb{R})$. Prove that $\|AB\|_{m,m} \leq \|A\|_{m,n} \|B\|_{n,m}$, where $\|\cdot\|_{m,n}$ is the norm induced by this scalar product on $\text{Mat}_{m \times n}(\mathbb{R})$.
- Let $\rho_P : \text{Mat}_{n \times n}(\mathbb{R}) \rightarrow \text{Mat}_{n \times n}(\mathbb{R})$ be the transformation defined by $\rho_P(A) = PAP^{-1}$, with $A \in \text{Mat}_{n \times n}(\mathbb{R})$ and $P \in O(n)$ (ρ_P is called *conjugation* by P). Prove that ρ_P is an isometry of $\text{Mat}_{n \times n}(\mathbb{R})$ with respect to the scalar product $\langle A, B \rangle = \text{trace}(A^T B)$ from part 1.